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SYSTEM TEST METHODOLOGY VOL. II

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APPENDIX A

DESCRIPTION OF PROTOTYPE TESTING SIMULATION MODEL

1. Definition of Terms

The following terms were defined in the text: state, module, task, and primary state. Their usage in this description of the simulation of the model will be consistent with these definitions. The status of a module was defined to be the information required to identify a particular module, and its state, that is executing a task for a given input. Thus, the status of a module identifies: module, state, task, and input number.

All time values in the program were based on the standard time unit. The standard time unit may be defined as the user desires. The only requirement is that the user must be consistent throughout the program and that all time values be integers.

2. Program Characteristics

The simulation of the model was an event store type of simulation. In this type of simulation the time is advanced each time an event occurs instead of on a fixed interval. This prevented the occurrence of a large number of intervals during which there was no activity. This type of simulation maintains the complete status of the system during the simulation because events are executed in the order in which they occur. The events in this simulation consisted of the arrival of inputs, the completion of a primary state, data collection events, and the termination event. The event that represented the completion of a primary state was always followed by the occurrence of the next primary state unless the input terminated or

the resources required to enter the next primary state were not available. A data collection event was a time period during which the user could measure any parameter of the simulation. These occurred at regular intervals throughout the running of the simulation and could be used to gather data to compute such statistics as average queue size.

The programming language chosen for the simulation language was FORTRAN IV. The reason for this choice was to ensure the portability of the program. FORTRAN is not an ideal programming language for simulation. Other languages such as GPSS (General Purpose Simulation System) provide many of the building blocks needed for the simulation such as the clock and the calendar. Although FORTRAN does not provide these blocks, it is readily available at most institutions. A limit to the portability of the program is the random number generator which was used in the simulation. The program used the LLRANDOM package available at the W. R. Church Computer Center. The random numbers were passed by subroutine calls. By adjusting these calls, a new random number generator may be introduced into the program.

The simulation was designed to be able to simulate a wide range of computer systems. This was implemented by allowing the user to input various characteristics of the system. These characteristics are discussed in the input section of the appendix. The resources used were identified throughout the program only by number. The user was to assign both the type of resources the system uses and the amount of each resource available to the system. The only requirement was that all quantities were to be integer values. The workload for the system was defined as a system of tasks. The user was required to specify the priority of tasks. Modules were identified by number. The user was to specify which module or modules was to execute each task. The user was also to specify which resources and primary states were required in the performance of each task.

The simulation was programmed in a modular fashion. Each major function of the simulation consisted of a separate subroutine. This design was chosen to facilitate modifications to the program and to improve the readability of the program. All major data structures and variables were made available to all subroutines by the use of common blocks.

3. Inputs

The simulation allowed the user to vary the input parameters listed below. The description is in the order in which the inputs were required by the program. If no range is given the parameter did not have limits placed upon it by the program. Limits were caused by the size of the data structure used in the program. The user could have chosen any reasonable value for the unlimited parameters. Subscripted variables indicate multi-dimensional data structures.

- * MAXIN --- Determined the number of inputs the system may process at one time. Range was one to ten inputs.
- * MEANIN --- Represented the mean interarrival time for the system. Units had to be standard time units.
- * NUMRES --- Total number of resources required by the system for proper functioning of the system plus one. The additional resource was the system time representation. This allowed the user to specify the amount of time the resources were in use. The range of NUMRES was from two to ten.
- * MAXRES(I) --- This vector gave the maximum amount of each resource available to the system. The units had to be in standard time units. The range of I was from one to NUMRES.

- * NUMTSK --- This was the number of tasks assigned to the system. The range was from one to ten tasks.
- * PRECTSK(I,J) --- This matrix was used to give the precedence relationships among tasks. Each column was identified by a task. This task blocks all tasks listed in the column. The first element of each column was the number of tasks blocked by the given task. For example, if column number three contained the following numbers reading from top down: 2, 4, 6. This would indicate task number three blocked two tasks, namely task four and task six. The variable I had a range from one to NUMTSK. J was confined to the same range.
- * MAXSEQ --- This was the maximum number of primary states that a module had to go through in order to execute a task. The range was one to eight states.
- * DOTSK(I,J) --- This matrix showed the different sequences of primary states that a module was required to go through to complete one task. Each row represented the path for one module to perform one task. The first element of a row was the task, the second element was the module, and the remaining elements were the sequence of primary states. A zero indicated the sequence had been completed. The variables I and J had a range of one to ten.

- * ENDTR --- This was the number of different primary states for every module. The maximum value was thirty.
- * TSKRES(I,J) --- This matrix gave the amount of each resource required for the execution of each primary state of a module and the associated task. Each row was the resources required by one task/state/module. Thus, the first three elements of each row represented the respective task, state, and module associated with the resource requirements given in that row. The first entry represented the time that the resources would be required in that state. The variable I had a range from one to ENDTR. The range of J was from one to NUMRES plus three.

The following parameters were assigned values in the start subroutine of the program and may be varied as the user desires:

- * MAXTIM --- This variable gave the total time the simulation was to be run. Units were standard time units. The value assigned was 1000000.
- * DATINV --- This variable was the time between data collection events. Units were standard time units. The value assigned was 2500. The user was free to choose any value for this parameter. However, the value chosen should be realistic in terms of the other time values used in the program.
- * IX --- This variable was the seed for the random number generator. It could have had a value

The system table was represented by a group of vectors. A vector was a one dimensional array that was used to store status information. The group of vectors was accessed by a common index. The index was stored on a separate vector in order of request for resources. Thus, a complete description of any module waiting for resources could be obtained without a sequential search of the table. This facilitated the user specification of service discipline.

The simulation calendar was represented by a group of vectors in the same manner as the system queue. Besides the information describing the status of modules that were in service, this group also contained vectors representing simulation information such as event type and event time. The event time was the time representing the scheduled completion of the event. The event type differentiated among end of state events, data collection events, arrival of input events, and termination events. A zero in this vector represented an empty slot on the simulation calendar. Each time an event was selected the event time vector was searched sequentially to determine the next event occurrence time in the simulation.

The event records represented a diverse group of data structures used to preserve information about the events in the simulation. The general form of these data structures were matrices with each row representing one input that was being processed by the system and a column for each data element to be preserved for each state. The data elements were items such as time input entered system, time module used resources in a primary state, and the order in which primary states were executed. In order to avoid being overwritten, these matrices had to be printed out at the end of each sequence of tasks. The column index to these matrices was based on the number of state transitions and each index was adjusted for the proper number of

elements being preserved in the matrix.

Utility records were used to save information as it was being moved from the system queue to the simulation calendar.

5. Output

Two types of output were provided for in the simulation of the model. These were event reports and sequential reports. The event reports occurred whenever the event with which they were associated was terminated. Three types of event reports were used in the simulation. These were end of state report, end of task sequence report and termination report.

The end of state report report occurred at the end of every primary state. The report contained the status of the module. The report gave timing information about the primary state just completed. This included the time the module was placed in the table, the time the module entered service, time the module finished service, total time in the system, total time in service, and total time in table. The report showed the amount of each resource available after the resources used in that state were returned to the system. A printout of the system table was shown after the next module status had been added to the table. All modules that were scheduled at that time were reported giving the status of each module. The report concluded with the status of all system resources after the scheduling activity had been completed.

The end of task sequence report occurred after the complete sequence of tasks for one input had been completed. The first part of the report gave the sequence of states, identifying each state by task and module. The second part of the report gave information about the timing of the task

sequence. This included the time the first module entered service, the time the last module finished processing, the total time required if the sequence of tasks had been processed serially, and the total time the input was in the system.

The termination report gave the total number of inputs that were lost by the system when it was already processing the maximum number of inputs allowed in the system. This report could be used to give averages from the data collection events such as average queue size and average percent of each resource being used by the system.

Sequential reports were not used by the simulation but could have been initiated by the data collection event and used to give an instantaneous status of the system at regular intervals.

6. Program Flow

The program commenced with a call to subroutine START. This subroutine initialized all the variables and returned control to the main program. The next event was selected by the subroutine NEXT. This subroutine selected an event based on a sequential search of the simulation calendar. Control was returned to the main program which called the appropriate subroutine to handle the selected event.

If the next event was an arrival of an input, subroutine NEWINP was called. Subroutine NEWINP inserted the first module status on the system table with a call to the subroutine PUTONQ. This occurred only if there was space in the system for another input and if there was room in the system table. If there was no space in the system, the input was counted as a lost input. If there was no room on the system table, the program was terminated with an error condition. With the exception of an error condition, the next

arrival of an input was placed on the simulation calendar with a call to the subroutine ENTER. A call was placed to the subroutine SKED. This subroutine ascertained whether currently available system resources were sufficient for a module on the system table to commence service. All modules were examined on a first-come-first served basis and as many as possible were placed in service. The end of state event was entered on the simulation calendar. Control was passed to the main program where the next event was selected.

The subroutine ENDSTT was called. The resources used by the module were returned to the system. If the completion of the state did not complete the task, the next module status was placed on the table and subroutine SKED was called. If the completion of the state completed the task, the next task was selected. The first module status of the task was placed on the system table and again SKED was called. In either case, STTDUMP was called to produce the end of state report. If the task was a termination task, subroutine DUMPIN was called to produce an end of task sequence report. Control was returned to the main program.

Two other types of events could occur. These were the data collection event and the termination event. A data collection event resulted in a call to subroutine WHAT. This subroutine collected the assigned information, scheduled the next data collection event, and returned control to the main program. The termination event occurred at the maximum simulation time and produced the termination report.

7. Desirable Features

The generality of the simulation, and hence its applicability to any real system, was restricted because certain parameter choices are not given to the user. These parameters included the queueing discipline, resource allocation policy and the distribution of time spent in a state. Ideally, there would

be many choices of these parameters with the user having the ability to specify the discipline, policy, and distribution that best represented the system he intended to test.

During the development of the program, other features that would have added to the usefulness of the simulation were discovered. One such feature was a debug package. This could include such items as a stall alarm. This alarm would give a warning if a module was in the system table for an excessive time period. The length of this time period could be selected and adjusted by the user. This alarm could be used to detect modules that were deadlocked or to set a maximum time that a module could be in the table before a failure occurred. Beizer [7] indicated various other alarms that would appear useful. These include watchdog timer alarms, cycle alarms, improper sequence alarms, and multiple or missed interrupt alarms (if the user chooses to simulate interrupts).

Another feature that would be useful is a restart capability. The status of the system at the termination of the simulation could be saved in a dump file. The user would be allowed to stop the system and make any observations he desired and restart from the same point. This ability would be particularly useful in investigating errors that occurred in a random fashion.

The above feature could be best utilized as an interactive program. The tester could watch the display of pertinent system data as the simulation operated. When an unusual occurrence was observed, the tester could stop the simulation and query parameters to determine what had taken place. Having made his observations, the tester would have the choice of restarting the simulation, continuing from the point of interruption, or saving the data produced on hard copy.

8. Limitation

The simulation that was programmed had a limitation for practical

use in testing. The limitation was the size of the system that could be represented. The number of tasks and other elements were limited. This was done to reduce turn-around time during the development of the program.

APPENDIX B

FORTRAN EXAMPLE PROGRAM CODE

Node	Code
	C SUBROUTINE FOR COMPUTING J-N, Y-N, I-N, AND K-N
	C ASYMPTOTIC EXPANSION IS USED FOR LARGE ARGUMENT
1	C SUBROUTINE BESSEL(X, NORD, BJN, BY, BIN, BK)
	PI = 3.14152927
	GAM = .57721566
2	C FN = NORD
	IF (X - FN - 6.) 1,200,200
	1 XA = X / 2.
	XB = XA * XA
	C COMPUTATION OF J-ZERO AND I-ZERO
	C N = 0
	C COMPUTATION OF J-N AND I-N BY POWER SERIES
	C
	3 AN = N
	T = 1.
	S = -1.
4	10 IF (AN) 9999,20,12
	12 T = T * XA / AN
	AN = AN - 1.
7,11	GO TO 10
	20 BJN = T
	BIN = T
8	DO 30 K = 1,K
	DEN = K * (K + N)
	T = T * XB / DEN
12	IF ((BJN + T) - BJN) 25,50,25
	25 BJN = BJN + T*S
	BIN = BIN + T
15	30 S = -S
14	C
17	C
	50 IF (N - 1) 75,130,55
	C K - N IS COMPUTED FROM ASYMPTOTIC EXPANSION
	C IF X IS GREATER THAN N + 3
	C
21	55 IF (X - FN - 3.) 1111,1111,200
	C CALCULATION OF J-1 AND I-1
	C
	65 N = 1
	BJO = BJN
	BIO = BIN
	BYO = BY
	BKO = BK
	GO TO 3

<u>Node</u>	<u>Code</u>
	C C C COMPUTATION OF K-ZERO AND Y-ZERO
	75 BY = 2./PI * (GAM + LOGF(XA)) * BJN BK = - (GAM + LOGF(XA)) * BIN T = XB S = 1. XI = 1.
22	DO 110 K = 2, K
	AK = K
25	IF ((BY + T*XI) - BY) 100, 120, 100
	100 BK = BK + T*XI BY = BY + 2./PI*S*T*XI T = T*XB / (AK*AK) XI = XI + 1./AK
28	110 S = -S
27	C C C
29	120 IF (NORD) 9999, 55, 65
	C C C COMPUTATION OF Y-1 AND K-1 BY WRONSKIAN FORMULAS
	130 BY = (BJN*BYO - 2./(PI*X)) / BJO BK = (1. / X - BIN*BKO) / BIO
	C C C Y-N AND K-N BY RECURSION FORMULAS FOR ORDERS HIGHER THAN ONE
20	P = 1. IF (NORD - 1) 9999, 55, 140 140 BY1 = BY BK1 = BK BY = 2.*P / X*BY1 - BYO BK = 2.*P / X*BY1 + BYO
	C P = P + 1.
23	IF (NORD - 2) 9999, 150, 146 146 BYO = BY1 BK = BK1 NORD = NORD - 1 GO TO 140
	C 150 N = P GO TO 3
	C

<u>Node</u>	<u>Code</u>	
	C	COMPUTATION OF J-N, I-N, K-N, AND Y-N
	C	BY ASYMPTOTIC EXPANSIONS
	C	
	200	C = 4 * NORD * NORD D = 8. * X CCN1 = SQRTF(2./(PI*X)) CON2 = 1./SQRTF(2.*PI*X) CON3 = SQRTF(PI/(2.*X)) AN = NORD PHI = X - (2.*AN + 1.) / 4. * PI M = X + 1. + SQRTF(X * X + AN * AN) T = (C - 1.) / D S = 1. U = 1. PN = 1. QN = T BK = 1. + T BI = 1. - T
3	C	DO 240 I = 2,M
		AI = 1
		T = (C - (2.*AI - 1.)**2) / D*T / AI
		BK = BK + T
		BI = BI + T*S
5	210	IF (S) 220,9999,210
		PN = PN - T*S*U
		U = -U
		GO TO 230
10	220	IF ((QN + T) - QN) 230,241,230
	230	QN = QN - T*S*U
	240	S = -S
12	240	CONTINUE
13	241	BK = EXPF(-X) * CON3 * BK
	C	
	C	ASYMPTOTIC EXPANSION IS USED ONLY FOR K-N
	C	IF X IS BETWEEN N + 3 AND N + 6
16	250	IF (X - FN - 6.) 1111,250,250
		BJN = CON1 * (PN*COSF(PHI) - QN*SINF(PHI))
		BY = CON1 * (PN*COSF(PHI) + QN*SINF(PHI))
		BIN = EXPF(X) * CON2 * BI
18,24	1111	NORD = FN
		RETURN
6,9,19, 26,30	C 9999	STOP
		END

APPENDIX C

DIRECTIONS FOR USE OF THE ERROR SIMULATION PROGRAM

Random numbers are drawn using the Naval Postgraduate School Random Number Generator Package LLRANDOM (NPS55LW73061A). These calls are RANDOM for a uniform distribution and EXPON for an exponential distribution.

Printer plots are drawn by the PLOTP routine which is part of the IBM supplied routines. Directed graph plots are drawn by the DRAWP routine available on the Naval Postgraduate School IBM 360/67 System connected to a CALCOMP plotter. The subroutine GRAPHO is limited because it requires the directed graph to be constructed in such a way that the rightmost leg of the tree is the longest leg, which means that the rightmost terminal node is the lowest node.

Histograms are plotted and analyzed by the HISTG routine available on the Naval Postgraduate School IBM 360/67. The functions SIN, COS and ATAN2 are standard IBM FORTRAN-supplied subroutines.

The analysis of loops in the simulation assumed that there were instructions in the arc from i to j and also in the backward arc from j to i. This may not be realistic, but does prove useful when simulating the actual path. When an input reaches a branch point that has a backward arc emanating from it, the model simulates a random number of iterations using the number of instructions in the backward

arc. After completing the simulated looping, it was possible to trace the same path or a different path if there were intermediate branch points. If the same path was selected, there was another chance for the backward arc to be selected. This is a common programming structure, where a loop is executed for so many iterations, a few parameters are changed and the loop is executed again for another or the same number of iterations.

The comment section of the simulation program, titled "Directions for Use", describes the use of each data input to the program as well as the common values utilized during this research. The numbers along the top of the cards (Figures C-1 to C-7) are the column numbers, the middle row of numbers are sample data and the bottom row of numbers is either the corresponding node for each piece of data or data item names. The formats used are shown below.

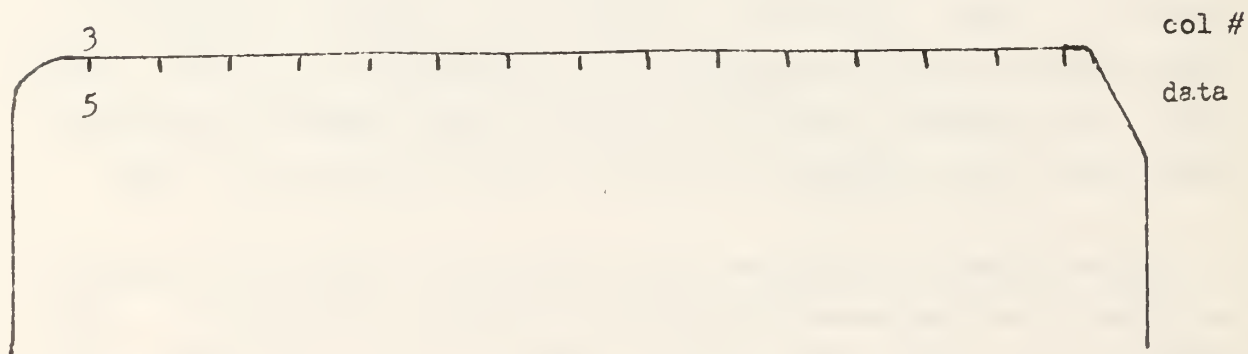


Fig C-1 Each item in paragraph A of the directions for use is on a separate card with I3 format except item A(12) which is A5 format (*****).

5	10	15	20	25	30	35	40	45	50	55	60	65	70	75	80	col #
0	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	data
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	node #

Fig C-2 Adjacency matrix card - 16I5 format.

5	10	15	20	25	30	35	40	45	50	55	60	65	70	75	80	col #
1	0	0	0	0	0	0	0	0	0	0	0	0	0	0		data
17	18	19	20	21	22	23	24	25	26	27	28	29	30			node #

Fig C-3 Second card of adjacency matrix - based on a graph with 30 nodes.

5	10	15	20	25	30	35	40	45	50	55	60	65	70	75	80	col #
0	0	10.	15.	0	0	0	0	0	0	0	0	0	0	0	0	data
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	node #

Fig C-4 Matrix of arc lengths data card - 16F5.0 format.

5	10	15	20	25	30	35	40	45	50	55	60	65	70	75	80	col #
2.	0	0	0	0	0	0	0	0	0	0	0	0	0	0		data
17	18	19	20	21	22	23	24	25	26	27	28	29	30			node #

FigC-5 Second card of the matrix of arc lengths - based on a graph with 30 nodes.

5	10	col #
22	29	data
N1	N2	id

FigC-6 The two nodes which determine the arc to be added or deleted from the structure - 215 format

10	col #
622150796	data
13	id

FigC-7 The seed for the random number generator - format 1110.

ERROR SIMULATION PROGRAM LISTING

D-1

```

B. INPUT ADJACENCY MATRIX
C. IF INREAD = 1 INPUT MATRIX OF ARC LENGTHS.

3. TO RUN THE SIMULATION WHICH VARIES THE NUMBER OF ARCS BETWEEN
THE NODES.
A. NORMAL DATA INCLUDES:
  (1). SIMNUM = 3
  (2). MINPUT = 3
  (3). MEANLN = 10
  (4). NUMOUT = 20
  (5). INREAD = 0
  (6). DELADD = 0
  (7). ITIME = 50
  (8). MATR = 30
  (9). MEANER = 20
  (10). MEANIT = 20
  (11). AVCHNG = 3
  (12). ASTER = *****
  (13). N = 30
  IF DELADD = 0 INPUT MOST COMPLEX STRUCTURED ADJACENCY
  MATRIX.
  IF DELADD = 1 INPUT SIMPLEST STRUCTURED ADJACENCY MATRIX.
  INPUT 20 (NUMOUT) PAIRS OF VALUES N1 AND N2 WHICH
  DETERMINE THE ARC TO BE DELETED OR ADDED.

4. TO RUN THE SIMULATION WHICH VARIES THE NUMBER OF LOOPS:
A. NORMAL DATA INCLUDES:
  (1). SIMNUM = 4
  (2). MINPUT = 3
  (3). MEANLN = 10
  (4). NUMOUT = 20
  (5). INREAD = 0
  (6). DELADD = 0
  (7). ITIME = 50
  (8). MATR = 30
  (9). MEANER = 20
  (10). MEANIT = 20
  (11). AVCHNG = 3
  (12). ASTER = *****
  (13). N = 30
  IF DELADD = 0 INPUT MOST COMPLEX STRUCTURED ADJACENCY
  MATRIX.
  IF DELADD = 1 INPUT SIMPLEST STRUCTURED ADJACENCY MATRIX.
  INPUT 20 (NUMOUT) PAIRS OF VALUES N1 AND N2 WHICH
  DETERMINE THE LOOP TO BE DELETED OR ADDED.

```

```

CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
5. TO RUN THE SIMULATION WHICH VARIES THE SEED TO THE INPUT:
A. NORMAL DATA INCLUDES:
  (1). SIMNUM = 5
  (2). MINPUT = 1
  (3). MEANLN = 10
  (4). NUMOUT = 30
  (5). INKREAD = 0 IF THE NUMBER OF INSTRUCTIONS IN EACH
      ARC IS TO BE DETERMINED RANDOMLY - OTHERWISE
      INKREAD = 1
  (6). DELADD = 0 (IN MILLISECONDS)
  (7). ITIME = 50 (IN MINUTES)
  (8). MMTK = 30
  (9). MEANR = 20
  (10). MEANIT = 20
  (11). AVCHNG = 3
  (12). ASTER = *****
  (13). N = 30
B. INPUT ADJACENCY MATRIX
C. IF INKREAD = 1 INPUT MATRIX OF ARC LENGTHS.
D. IZ = 1722632 (OR WHATEVER LAST SEED WAS ON PREVIOUS RUN)
NOTE: LAST DATA CARD
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
COMMON/ALL/N, NODES(30,30)
COMMON/ARRAY/X(30,30), NUMPTS(30), ASTOUT(30), AVCHNG
COMMON/ERROR/ISEED(30,30), ITER(30,30), MEANER, INST, MEANIT, IZ
COMMON/OUT/INSEED, INPUT, SVSEED(30,30)
COMMON/GEN/MEANLN, IX
COMMON/NEW/IN
COMMON/GRAP/INKREAD
DIMENSION ITIME(50), TREP(50), ILINK(50), TKOUNT(50), TINPUT(50)
DIMENSION PSEED(50), FNA(50), FLA(50)
DIMENSION ISEED(50), TINST(50), PTEST(50)
INTEGER*4 CHNG, AVCHNG, TESTED(30,30), TEST, SIMNUM, SVSEED
INTEGER*4 DELADD
REAL*4 MTRR
FORMAT (I3)
100 FFORMAT (I10)
108 FFORMAT (I16I5)
140 FFORMAT ('1', 13X, 'THIS RUN WILL VARY THE NUMBER OF INSTRUCTIONS B
151 FFORMAT ('1', 13X, 'THIS RUN WILL VARY THE NUMBER OF INPUTS TO BE U
152 FFORMAT ('1', 13X, 'THIS RUN WILL VARY THE NUMBER OF ARCS BETWEEN T
153 FFORMAT ('1', 13X, 'THIS RUN WILL VARY THE NUMBER OF LOOPS.')
154 FFORMAT ('1', 13X, 'THIS RUN WILL VARY THE RANDOM NUMBER SEED WHICH
155 FFORMAT ('1', 13X, 'THE INPUT PATH.')
1 DETERMINES

```

```

156 FORMAT ('0', 13X, 'THE NUMBER OF INSTRUCTIONS IN EACH ARC HAS BEEN
1 READ IN AND IS NOT RANDOM.')
180 FORMAT ('0', 13X, 'ADJACENCY MATRIX'//7X, 30(I4))
203 FORMAT ('0', 13X, 'NOTE: NONEXISTENCE OF AN ARC IS INDICATED BY A
1 ZERO'//)
204 FORMAT ('0', 13X, 'THERE WILL BE', 13, ' GRAPHS EVALUATED THIS RUN
1'//)
205 FORMAT (7(I5, 5X))
206 FORMAT (A5)
207 FORMAT ('0', 12X, 'INPUT ASSUMPTIONS (VARIABLES):'//13X, 'EXECUTIO
IN TIME PER INSTRUCTION HAS AN EXPONENTIAL DISTRIBUTION WITH A MEAN
2 OF', 13, 'MILLISECONDS'//13X, 'MEAN TIME TO REPAIR AN ERROR HAS
3 AN EXPONENTIAL DISTRIBUTION WITH A MEAN OF', 13, 'MINUTES'//13X,
4 'THE NUMBER OF INPUT PATHS BEING INVESTIGATED IS', 13, '13'//13X,
5 'ERRORS ARE SEEDED BY AN EXPONENTIAL DISTRIBUTION WITH A MEAN OF',
6 '13'//13X, 'THE AVERAGE NUMBER OF INSTRU
7CTIONS INSTRUCTIONS PER ERROR IS FOUND IS', 13, '13'//)
208 FORMAT ('0', 13X, 'THE NUMBER OF ITERATIONS PER LOOP IS UNIFORMLY
1 DISTRIBUTED FROM 1 TO', 13, '13'//)
209 FORMAT ('0', 13X, 'THE MEAN NUMBER OF INSTRUCTIONS BETWEEN EACH NO
1DE IS EXPONENTIALLY DISTRIBUTED WITH A MEAN OF', 13, '13'//)
227 FORMAT ('0', 13X, 'SAMPLE INPUT PATH FROM'//13X, 'NODE TO NODE'//)
230 FORMAT ('0', 11X, 14, 4X, 14)
240 FORMAT ('0', 13X, 'FOR INPUT NUMBER', 13, 'THE EXECUTION TIME IS',
1 F8.2, 'SECONDS WITH A TOTAL REPAIR TIME OF', F8.2, ' HOURS'
2 // 13X, 'AND AN AVERAGE LINK TRAVERSAL TIME OF', F8.2, ' SECONDS')
245 FORMAT ('0', 13X, 14, 'SEDED ERRORS REMAINING'//13X, 'MATRIX OF
250 FORMAT (1, 13X, 14, 'ERROR FOUND'//)
1 SEDED ERRORS REMAINING'//7X, 30(I4))
255 FORMAT ('0', 7X, 15, '30(I4)')
260 FORMAT ('0', 11X, 13, 'INPUTS'//13X, 14, ' INSTRUCTIONS'//13X,
265 FORMAT (1, 13X, 13, 'RESIDUAL ERRORS'//13X, F6.2,
13, 'PERCENT RESIDUAL ERRORS'//13X, F6.2, ' PERCENT OF ARCS TESTED'
2 //)
270 FORMAT ('0', 9X, F10.5, ' SECONDS EXECUTION TIME'//12X, ' SECONDS AVE
1 F10.5, ' HOURS TO REPAIR ERRORS'//12X, F10.6, ' SECONDS AVE
2RAGE ARC TRAVERSAL TIME'//)
275 FORMAT ('0', 12X, F5.2, ' IS THE RATIO OF ACTUAL TO MAXIMUM NUMBER
1 OF ARCS'//13X, F5.2, ' IS THE RATIO OF NODES TO ARCS'//13X,
2 F5.2, ' IS THE RATIO OF LOOPS TO ARCS'//)
280 FORMAT ('0'//13X, 'HISTOGRAM FOR EXECUTION TIME')
281 FORMAT ('0'//13X, 'HISTOGRAM FOR REPAIR TIME')
282 FORMAT ('0'//13X, 'HISTOGRAM FOR PERCENT RESIDUAL ERRORS')
283 FORMAT ('0'//13X, 'HISTOGRAM FOR PERCENT ARCS TESTED')
284 FORMAT ('1', 1X)
285 FORMAT ('0'//13X, 'EXECUTION TIME VS RESIDUAL ERRORS')
286 FORMAT ('0'//13X, 'EXECUTION TIME VS PERCENT RESIDUAL ERRORS')

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287 FORMAT ('0'//13X, 'REPAIR TIME VS RESIDUAL ERRORS')
288 FORMAT ('0'//13X, 'NUMBER OF INPUTS VS RESIDUAL ERRORS')
289 FORMAT ('0'//13X, 'NUMBER OF INSTRUCTIONS VS RESIDUAL ERRORS')
290 FORMAT ('0'//13X, 'RATIO OF ACTUAL TO MAXIMUM NUMBER OF ARCS VS RE
)SIDUAL ERRORS')
291 FORMAT ('0'//13X, 'RATIO OF NODES TO ARCS VS RESIDUAL ERRORS')
292 FORMAT ('0'//13X, 'RATIO OF LOOPS TO ARCS VS RESIDUAL ERRORS')
293 FORMAT ('0'//13X, 'EXECUTION TIME VS RATIO OF ACTUAL TO MAXIMUM NUM
)BER OF ARCS')
294 FORMAT ('0'//13X, 'EXECUTION TIME VS RATIO OF NODES TO ARCS')
295 FORMAT ('0'//13X, 'EXECUTION TIME VS RATIO OF LOOPS TO ARCS')
296 FORMAT ('0'//13X, 'NUMBER OF INPUTS VS PERCENT OF ARCS TESTED')
297 FORMAT ('0'//13X, 'RATIO OF ACTUAL TO MAXIMUM NUMBER OF ARCS VS PE
)RCENT OF ARCS TESTED')
298 FORMAT ('0'//13X, 'RATIO OF NODES TO ARCS VS PERCENT OF ARCS TESTE
)D')
299 FORMAT ('0'//13X, 'RATIO OF LOOPS TO ARCS VS PERCENT OF ARCS TESTE
)D')
300 FORMAT ('0'//13X, 'NUMBER OF INPUTS VS EXECUTION TIME')
301 FORMAT ('0'//13X, 'NUMBER OF INPUTS VS PERCENT RESIDUAL ERRORS')
302 FORMAT ('0'//13X, 'EXECUTION TIME VS NUMBER OF INSTRUCTIONS')
303 FORMAT ('1'//59X, 'DATA SUMMARY', //62X, 'PERCENT', 3X, 'PERCENT',
) 2X, 'EXECUTION', 5X, 'REPAIR', 4X, 'ACTUAL', 4X, 'NODES', 5X,
) 2X, 'LOOPS', 4X, 'RUN', 35X, 'ERRORS', 3X, 'RESIDUAL', 2X, 'TO', 8X,
) 4X, 'ARCS', 6X, 'TIME', 6X, 'TO MAX', 6X, 'TO', 8X,
) 5X, 'NUMBER', 5X, 'NODES', 4X, 'INPUTS', 4X, 'INSTR', 4X, 'SEED',
) 6X, 'ERRORS', 4X, 'ARCS', 4X, 'TESTED', 4X, '(SEC)', 7X,
) 7X, '(HRS)', 4X, 'ARCS', 6X, 'ARCS')
304 FORMAT ('0'//13X, '1X, 13, 5X, 13, 7X, F5.0, 3(5X, F5.0),
) 2(4X, F6.2), 2X, 2F10.5, 3X, F5.3, 2(5X, F5.3)')
305 READ IN THE TYPE OF SIMULATION TO BE RUN (SIMNUM)
) READ (5,100) SIMNUM
) READ IN NUMBER OF INPUTS TO BE USED (MINPUT)
) READ (5,100) MINPUT
) READ IN THE MEAN NUMBER OF INSTRUCTIONS BETWEEN EACH NODE (MEANLN)
) READ (5,100) MEANLN
) READ IN THE NUMBER OF GRAPHS TO BE EVALUATED (NUMOUT)
) READ (5,100) NUMOUT
) READ IN WHETHER OR NOT THE NUMBER OF INSTRUCTIONS IS TO BE READ IN
) READ (5,100) IREAD
) READ IN WHETHER DELETING AN ARC FROM THE STRUCTURE OR
) ADDING AN ARC TO THE STRUCTURE.
) READ (5,100) DELADD
) READ IN THE MEAN TIME TO EXECUTE AN INSTRUCTION IN MILLISECONDS
) (ITIME)
) READ (5,100) ITIME

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C      IN MEAN TIME TO REPAIR AN ERROR IN MIN (MMTTR)
C      READ (5,100) MMTTR
C      READ IN MEAN NUMBER OF INSTRUCTIONS THAT ARE ERROR FREE (MEANER)
C      READ (5,100) MEANER
C      READ IN MEAN NUMBER OF ITERATIONS FOR EACH LOOP (MEANIT)
C      READ (5,100) MEANIT
C      READ IN MEAN NUMBER OF INSTRUCTIONS CHANGED WHEN AN ERROR IS
C      FOUND (AVCHNG)
C      READ (5,100) AVCHNG
C      READ IN THE ASTERICKS TO PUT AROUND OUTPUT ARRAYS (ASTER)
C      READ (5,206) ASTER
C      READ IN THE NUMBER OF NODES (N)
C      READ (5,100) N
C      READ IN THE ADJACENCY MATRIX (NUDES)
      DO 20 I=1,N
      READ (5,140) (NODES(I,J), J=1,N)
      IF (SIMNUM.EQ.1) WRITE (6,151)
      IF (SIMNUM.EQ.2) WRITE (6,152)
      IF (SIMNUM.EQ.3) WRITE (6,153)
      IF (SIMNUM.EQ.4) WRITE (6,154)
      IF (SIMNUM.EQ.5) WRITE (6,155)
      IF (SIMNUM.EQ.1) WRITE (6,156)
      WRITE (6,207) ITIME, MINPUT, MEANER, AVCHNG
      WRITE (6,208) MEANIT
      WRITE (6,209) MEANLN
      WRITE (6,204) NUMOUT
      NUMOUT = 1
      IX = 71286223
      IW = IX
C      DETERMINE THE MAXIMUM NUMBER OF ARCS IN THE ADJACENCY MATRIX
C      MAXARC = N*(N-1)
C      NUMPTS IS THE LABEL FOR THE OUTPUT ARRAY
      DO 57 I = 1,N
      NUMPTS(I) = 1
      ASTER AND ASTOUT ARE TO PUT ASTERICKS AROUND THE ARRAY
      ASTOUT(I) = ASTER
      CONTINUE
57  CALL OIGRAF
59  DO 52 I = 1,N
      DO 61 J = 1,N
      ISEED IS THE ARRAY OF ERRORS SEEDED
      ISEED(I,J) = 0
      CONTINUE
61  CONTINUE
62  SEED THE PROGRAM WITH ERRORS
      IF (SIMNUM.EQ.1) IX = 1722632
      CALL SLED
C      THIS SEED CAN BE CHANGED TO THE LAST VALUE OF THE SEED ON THE

```

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C      PREVIOUS TEST IF A CONTINUATION OF THE DATA IS DESIRED.
63  IF (SIMNUM.EQ.5) READ (5,108) IX
    INST = 0
    NSEED = 0
    DO 65 I=1,N
      DO 65 J=1,N
        ZERO THE MATRIX WHICH RECURDS WHETHER OR NOT AN ARC HAS BEEN TEST
        TESTED(I,J) = 0
        IF (NODES(I,J).NE.1) GO TO 65
        CALCULATE THE NUMBER OF ARCS IN THE PROGRAM
        ARCS = ARCS + 1
        CALCULATE THE NUMBER OF INSTRUCTIONS
        INST = INST + X(I,J)
        CALCULATE THE NUMBER OF ERRORS SEEDD
        NSEED = NSEED + ISEED(I,J)
        CONTINUE
        CALCULATE THE NUMBER OF LOUPS IN THE PROGRAM
        LOOPS = 0
        DO 68 I=1,N
          DO 68 J=1,I
            IF (NODES(I,J).EQ.1) LOOPS = LOOPS + 1
        CONTINUE
        CHOOSE SAMPLE INPUT
        INPUT = 1
        TOTREP = 0
        TIME = 0
        AVLINK = 0
        TTIME(NNOUT) = 0
        TREP(NNOUT) = 0
        TLINK(NNOUT) = 0
        IZ = IX
        NODE = 1
        WRITE (6,227)
        NUMSUC IS THE NUMBER OF SUCCESSORS
        NUMSUC = 0
        DO 80 J=1,N
          IF (NODES(NODE,J).EQ.1) NUMSUC = NUMSUC + 1
        CONTINUE
        IF (NUMSUC.EQ.0) GO TO 96
        IF (NUMSUC.NE.1) GO TO 82
        K = 1
        GO TO 83
        THE SUCCESSORS ARE CHOSEN RANDOMLY WITH A UNIFORM DISTRIBUTION
        CALL RANDOM(IZ,U,1)
        K = 1 + NUMSUC*U
        KK = 0
        DC 85 J = 1,N

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      IF (NODES(NODE,J).EQ.1) KK = KK + 1
      IF (KK.EQ.K) GO TO 86
      CONTINUE
35  L = J
86  TIME IS ASSUMED TO HAVE A MEAN OF ITIME MILLISECONDS PER
      INSTRUCTION WITH AN EXPONENTIAL DISTRIBUTION
      CALL EXPON(IZ, XTIME, 1)
      XTIME = XTIME * ITIME
      IF (NODE.LE.L) GO TO 88
      CURVERT TIME INTO HOURS
      TIME = TIME + XTIME * ITER(NODE,L) * (X(NODE,L) + X(L,NODE)) /
1    1.0E03
      GO TO 89
88  TIME = TIME + X(NODE,L) * XTIME / 1.0E03
89  WRITE (6,230) NODE,L
      TESTED(NODE,L) = 1
      IS THERE AN ERROR IN THIS PATH
      IF (ISEED(NODE,L).EQ.0) GO TO 95
      ERROR FOUND
      WRITE (6,245)
      STOP IF A NEW ERROR SHOULD BE INSERTED
      CALL NUSEED
      ISEED(NODE,L) = ISEED(NODE,L) - 1
90  CALL EXPON(IZ, U, 1)
      MEAN TIME TO REPAIR HAS AN EXPONENTIAL DISTRIBUTION WITH A
      MEAN OF MTTR MINUTES
      MTTR = MTTR * U
      TOTREP IS THE TOTAL REPAIR TIME IN HOURS
      TOTREP = TOTREP + MTTR / 60.
      GO TO 78
95  NODE = L
      GO TO 79
      C AVLINK IS THE AVERAGE ARC TRAVERSAL TIME IN MINUTES
96  AVLINK = (TIME/ARCS)
      WRITE (6,240) INPUT, TIME, TOTREP, AVLINK
      IF (SIMNUM.EQ.2) GO TO 97
      ITIME(NNOUT) = ITIME(NNOUT) + TIME
      TREP(NNOUT) = TREP(NNOUT) + TOTREP
      TLINK(NNOUT) = TLINK(NNOUT) + AVLINK
      GO TO 99
97  NOUT = NNOUT - 1
      IF (NOUT.GE.1) GO TO 98
      TLINK(1) = AVLINK
      TREP(1) = TOTREP
      ITIME(1) = TIME
      GO TO 99
98  TLINK(NNOUT) = TLINK(NOUT) + AVLINK
      TREP(NNOUT) = TREP(NOUT) + TOTREP

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99      TTIME(NNOUT) = TTIME(NNOUT) + TIME
      TIME = 0.
      TOTKEP = 0.
      AVLINK = 0.
      INPUT = INPUT + 1
      KOUNT IS A COUNTER OF THE NUMBER OF SEEDED ERRORS REMAINING
      KOUNT = 0
      DO 101 I = 1, N
      DO 101 J = 1, N
      IF (NODES(I,J).EQ.1) KOUNT = KOUNT + ISEED(I,J)
101      CONTINUE
      WRITE (6,250) KOUNT, (NUMPTS(I), I = 1, N)
      WRITE (6,255) (ASTOUT(I), I = 1, N)
110      DO 110 I = 1, N
      WRITE (6,260) NUMPTS(I), (ISEED(I,J), J=1,N)
      DISTINCT SEED FOR RANDOM NUMBER GENERATOR FOR EACH INPUT
      IX = IX - 12345
      IF (SIMNUM.EQ.2) GO TO 111
      IF (SIMNUM.EQ.5) GO TO 111
      MINPUT IS THE MAXIMUM NUMBER OF INPUT PATHS TO BE CHECKED
      IF (INPUT.LE.MINPUT) GO TO 78
      CALCULATE THE NUMBER OF ARCS TESTED
111      TEST = 0
      DO 112 I = 1, N
      DO 112 J = 1, N
      IF (TESTED(I,J).EQ.1) TEST = TEST + 1
112      CONTINUE
      INPUT = INPUT - 1
      PTEST IS THE PERCENT OF ARCS TESTED
      PTEST(NNOUT) = 100.*TEST/ARCS
      F IS THE RATIO OF ACTUAL TO MAXIMUM NUMBER OF ARCS
      F(NNOUT) = ARCS / MAXARC
      FNA IS THE RATIO OF NODES TO ARCS
      FNA(NNOUT) = N / ARCS
      FLA IS THE RATIO OF LOOPS TO ARCS
      FLA(NNOUT) = LOOPS / ARCS
      INST(NNOUT) = INST
      INPUT(NNOUT) = INPUT
      TSEED(NNOUT) = NSEED
      TKOUNT(NNOUT) = KOUNT
      PSEED(NNOUT) = 100.* (TKOUNT(NNOUT) / NSEED)
      WRITE (6,265) INPUT, INST, NSEED, KOUNT, PSEED(NNOUT),
1      PTEST(NNOUT)
      WRITE (6,270) TTIME(NNOUT), TREP(NNOUT), TLINK(NNOUT)
      WRITE (6,275) F(NNOUT), FNA(NNOUT), FLA(NNOUT)
      ANOUT = NNOUT + 1
      IF (NNOUT.GT.NUMOUT) GO TO 118
      IF (SIMNUM.EQ.1) MEANLN = MEANLN + 1

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```

IF (SIMNUM.EQ.1) GO TO 57
IF (SIMNUM.EQ.2) INPUT = INPUT + 1
IF (SIMNUM.EQ.2) GO TO 78
DO 113 I = 1,N
DO 113 J = 1,N
113 ISEED(I,J) = SVSEED(I,J)
IF (SIMNUM.EQ.5) GO TO 63
115 IF (DELADD.EQ.0) CALL DELARC
IF (DELADD.EQ.1) CALL ADDARC
116 WRITE (6,180) (NUMPTS(I), I=1,N)
WRITE (6,255) (ASTOUT(I), I=1,N)
DO 117 I = 1,N
117 WRITE (6,260) NUMPTS(I), (NODES(I,J), J=1,N)
WRITE (6,203)
GO TO 63
118 WRITE (6,305) IZ
WRITE (6,284)
CALL PLCTP (TIME, TKOUNT, NUMOUT, 0)
WRITE (6,285)
WRITE (6,287)
CALL PLCTP (TIME, PSEED, NUMOUT, 0)
WRITE (6,286)
WRITE (6,284)
CALL PLCTP (TREP, TKOUNT, NUMOUT, 0)
WRITE (6,287)
IF (SIMNUM.NE.2) GO TO 119
WRITE (6,284)
CALL PLCTP (INPUT, TKOUNT, NUMOUT, 0)
WRITE (6,288)
WRITE (6,284)
CALL PLCTP (INPUT, PTEST, NUMOUT, 0)
WRITE (6,296)
WRITE (6,284)
CALL PLCTP (INPUT, TIME, NUMOUT, 0)
WRITE (6,300)
WRITE (6,284)
CALL PLCTP (INPUT, PSEED, NUMOUT, 0)
WRITE (6,301)
119 IF ((SIMNUM.EQ.2).OR.(SIMNUM.EQ.5)) GO TO 121
WRITE (6,284)
CALL PLCTP (TIME, TINST, NUMOUT, 0)
WRITE (6,302)
WRITE (6,284)
CALL PLCTP (TINST, TKOUNT, NUMOUT, 0)
WRITE (6,289)
IF (SIMNUM.EQ.1) GO TO 121
WRITE (6,284)
CALL PLCTP (F, TKOUNT, NUMOUT, 0)

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WRITE (6,290)
WRITE (6,284)
CALL PLOTP (FNA, TKOUNT, NUMOUT, 0)
WRITE (6,291)
WRITE (6,284)
CALL PLOTP (FLA, TKOUNT, NUMOUT, 0)
WRITE (6,292)
WRITE (6,284)
CALL PLOTP (TTIME, F, NUMOUT, 0)
WRITE (6,293)
WRITE (6,284)
CALL PLOTP (TTIME, FNA, NUMOUT, 0)
WRITE (6,294)
WRITE (6,284)
CALL PLOTP (TTIME, FLA, NUMOUT, 0)
WRITE (6,295)
WRITE (6,284)
CALL PLOTP (F, PTEST, NUMOUT, 0)
WRITE (6,297)
WRITE (6,284)
CALL PLOTP (FNA, PTEST, NUMOUT, 0)
WRITE (6,298)
WRITE (6,284)
CALL PLOTP (FLA, PTEST, NUMOUT, 0)
WRITE (6,299)
121 DO 125 K=1,2
WRITE (6,303)
WRITE (6,255) (ASTOUT(I), I = 1,N)
DO 122 I=1,NUMOUT
122 WRITE (6,304) I, N, TINPUT(I), TINST(I), TSEED(I), TKOUNT(I),
1 PSEED(I), PTEST(I), TTIME(I), F(I), FNA(I), FLA(I)
125 CONTINUE
IF ((SIMNUM.NE.3).AND.(SIMNUM.NE.4)) CALL GRAPHO
NEED A MINIMUM OF 10 GRAPHS TO ANALYZE BEFORE CALLING HISTG
IF (SIMNUM.NE.5) GO TO 126
CALL HISTG (TTIME, NUMOUT, 0)
WRITE (6,280)
CALL HISTG (TREP, NUMOUT, 0)
WRITE (6,281)
CALL HISTG (PSFED, NUMOUT, 0)
WRITE (6,282)
CALL HISTG (PTEST, NUMOUT, 0)
WRITE (6,283)
126 CCNTINUE
C
C STOP
C
END

```



```

C      SPREAD ERRORS TO GIVE MEAN OF MEANER
C
60      DO 60 I = 1,N
        IER(I) = MEANER * ER(I)
        CONTINUE
C      I1 = 1
C      NSEED = 0 IS THE NUMBER OF ERRORS SEED
C      NSEED = 0
C      INST = 0 IS THE NUMBER OF INSTRUCTIONS
C      INST = 0
C      NUMER = 0 IS THE ERROR SEED/INSTRUCTION COMPARATOR
C      NUMER = 0
C      DO 70 I = 1,N
C      DO 65 J = 1,N
        IF (MODES(I,J).EQ.0) GO TO 65
        COUNT THE NUMBER OF INSTRUCTIONS
        INST = INST + X(I,J)
C      LOOPS ARE ASSUMED TO HAVE AN ERROR RATE PROPORTIONAL TO THE
C      NUMBER OF INSTRUCTIONS IN THE LOOP AND THE NUMBER OF ITERATIONS
C      THROUGH THE LOOP
        IF (J.LE.1) IER(II) = IER(II) / ( X(I,J) * IER(I,J))/MEANER)
63      NUMER = NUMER + IER(II)
        IF (INST.LT.NUMER) GO TO 64
        ISEED(I,J) = ISEED(I,J) + 1
        NSEED = NSEED + 1
        II = II + 1
        IF (II.LE.N) GO TO 63
        II = 1
        GO TO 63
C      GO TO 63
64      NUMER = NUMER - IER(II)
65      CONTINUE
70      CONTINUE
C      DO 71 I = 1,N
C      DO 71 J = 1,N
        SAVE COPY OF THE ORIGINAL SEEDED ERRORS
        ISEED(I,J) = ISEED(I,J)
        NSEED IS THE NUMBER OF ERRORS SEED
        INST
        WRITE (6,210) (IER(I), I = 1,N)
        WRITE (6,205) (IER(I), I = 1,N)
        WRITE (6,220) NSEED, (NUMPTS(I), I = 1,N)
        WRITE (6,222) (ASTOUT(I), I=1,N)
        DO 75 I = 1,N
        WRITE (6,225) NUMPTS(I), (ISEED(I,J), J=1,N)
75      CONTINUE
C      RETURN
C      END

```



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END
SUBROUTINE GRAPHO
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
C      GRAPHICALLY DISPLAY THE DIRECTED GRAPH USING THE CALCOMP PLOTTER C
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
C
COMMON/ALL/N, NODES(30,30)
DIMENSION ND(30,30), X(30), XX(2), Y(30), YY(2)
DIMENSION XL(36), YL(36), THETA(36)
INTEGER*4 ITB(12)/12*0/
REAL*4 RTB(28)/28*0.0/
ITB IS DRAWP ARRAY
ITB(1) = 1
ITB(2) = 0
ITB(3) = 5
ITB(4) = 15
ITB(8) = 2
ITB(9) = 0
ITB(10) = 2
ITB(11) = 0
RTB IS DRAWP ARRAY
RTB(1) = 1.0
RTB(2) = 1.0
DO 4 I = 1,N
DO 4 J = 1,N
ND(I,J) = 0
4 CONTINUE
X(1) = 4.5
Y(1) = 15.0
X(2) = X(1)
CONST = 30./N
Y(2) = Y(1) - CONST
CALL DRAWP(2,X,Y,ITB,RTB)
XCONST = 1.5
KOUNT IS X-DIRECTION SHRINK FACTOR - SHRINKS AFTER EVERY OTHER
FANOUT
KOUNT = 1
LEVEL IS THE LEVEL IN THE DIRECTED GRAPH
LEVEL = 2
NN = N - 1
ITB(1) = 2
LABEL IS THE NUMBER OF EACH NODE
LABEL = 2
DO 5 M = 1,N
IF (NODES(1,M).EQ.0) GO TO 5

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C      IS THE LAST NODE IN THE GIVEN LEVEL
KK = M
KT = KK + 1
IF (NODES(I,KT).EQ.0) GO TO 6
5  CONTINUE
C      IS THE LAST NODE IN THE NEXT LEVEL
6  DO 7 M = KK,N
   IF (NODES(KK,M).EQ.0) GO TO 7
   KM = M
   KX = KM + 1
   IF (NODES(KK,KX).EQ.0) GO TO 8
7  CONTINUE
8  DO 50 I = 2,NIN
   II = I - 1
   NUMSUC IS THE NUMBER OF SUCCESSORS
   NUMSUC = 0
   DO 20 J = I,KM
   IF (NODES(I,J).EQ.0) GO TO 20
   DO 18 K = I,II
   IS THERE A NODE ALREADY IN EXISTENCE
   IF (ND(K,J).EQ.0) GO TO 18
   CONNECT NEW NODE TERMINATING AT EXISTING NODE
17  XX(1) = X(I)
   XX(2) = X(J)
   YY(1) = Y(I)
   YY(2) = Y(J)
   CALL DRAWP(2,XX,YY,ITB,RTB)
   ND(I,J) = 1
   GO TO 20
18  CONTINUE
   NUMSUC = NUMSUC + 1
20  CONTINUE
C      IF (NUMSUC.LE.0) GO TO 44
25  IF (NUMSUC.NE.1) GO TO 30
   FANOUT TO ONE NEW NODE
   L = LABEL + 1
   LABEL = LABEL + 1
   ND(I,L) = 1
   X(L) = X(I)
   Y(L) = Y(I) - CONST
   XX(1) = X(I)
   XX(2) = X(L)
   YY(1) = Y(I)
   YY(2) = Y(L)
   CALL DRAWP(2,XX,YY,ITB,RTB)
   IS THERE A NODE ABOVE THAT NEEDS CONNECTING TO THIS NODE
   DO 23 K = 1,II
   IF (ND(K,L).EQ.1) GO TO 28

```



```

IF (NODES(K,L).EQ.0) GO TO 28
XX(1) = X(K)
YY(1) = Y(K)
XX(2) = X(L)
YY(2) = Y(L)
ND(K,L) = 1
CALL DRAWP(2,XX,YY,ITB,RTB)
C CONTINUE
28 GO TO 44
C
FANGUT TO MULTIPLE NODES
30 FAN = 2.*XCUNST / (NUMSUC - 1)
DO 35 L=1,NUMSUC
M = LABEL + L
ND(I,M) = 1
IF (L.GT.1) GO TO 31
X(M) = X(I) - XCUNST
GO TO 33
31 LM = M - 1
X(M) = X(LM) + FAN
33 Y(M) = Y(I) - CONST
XX(1) = X(I)
YY(1) = Y(I)
XX(2) = X(M)
YY(2) = Y(M)
CALL DRAWP(2,XX,YY,ITB,RTB)
C IS THERE A NODE ABOVE THAT NEEDS CONNECTING TO THIS NODE
DO 34 K=1,11
IF (ND(K,M).EQ.1) GO TO 34
IF (NODES(K,M).EQ.0) GO TO 34
XX(1) = X(K)
YY(1) = Y(K)
XX(2) = X(M)
YY(2) = Y(M)
ND(K,M) = 1
CALL DRAWP(2,XX,YY,ITB,RTB)
C CONTINUE
34 CONTINUE
35 LABEL = LABEL + NUMSUC
KOUNT = KOUNT + 1
40 IF (KOUNT.LT.2) GO TO 44
C REDUCE THE X-DIRECTION SCALE FACTOR
XCUNST = XCUNST/1.5
KOUNT = 0
C IS THIS NODE STILL ON THE GIVEN LEVEL
44 IF (I.I.KK) GO TO 50
C NO, CHANGE LEVELS
LEVEL = LEVEL + 1
C DETERMINE THE LAST NODE IN THE NEW LEVEL

```

```

45 M = I,N
IF (NODES(I,M).EQ.0) GO TO 45
KK = M
KT = KK + 1
IF (NODES(I,KT).EQ.0) GO TO 46
45 CONTINUE
DETERMINE THE LAST NODE IN THE NEXT LEVEL AFTER THE PRESENT LEVEL
46 DO 47 M = KK,N
IF (NODES(KK,M).EQ.0) GO TO 47
KM = M
NX = KM + 1
IF (NODES(KK,KX).EQ.0) GO TO 50
47 CONTINUE
50 CONTINUE
GRAPH LOOPS
DO 90 I = 2,N
K = I - 1
DC 80 J = 1,K
IF (NODES(I,J).EQ.0) GO TO 80
PI = 3.1415926
ESTABLISH THE DIRECTION OF CURVE FOR LOOP
IF (X(I).LT.X(J)) PI = -PI
STARTING POINT FOR CURVE
XL(I) = X(I)
YL(I) = Y(I)
XL(35) = X(J)
YL(35) = Y(J)
XDIF AND YDIF ARE THE DIFFERENCE BETWEEN THE X AND Y VALUES RESP.
XDIF = X(I) - X(J)
YDIF = Y(I) - Y(J)
R IS THE RADIUS OF THE LOOP
R = 0.5 * SQRT(XDIF**2 + YDIF**2)
(XC,YC) IS THE CENTER OF THE LOOP
XC = (X(I) + X(J))/2.
YC = (Y(I) + Y(J))/2.
THETE(1) IS THE INITIAL ANGLE
THETA(1) = ATAN2(YDIF,XDIF)
CREATE 36 POINTS IN A SEMICIRCLE FORMING THE LOOP
DO 70 L = 2,35
M = L - 1
THETA(L) = THETA(M) + PI/35.
XL(L) = R * COS (THETA(L)) + XC
YL(L) = R * SIN (THETA(L)) + YC
70 CONTINUE
CALL DRAWWP(36,XL,YL,LIB,RTB)
80 CONTINUE
90 CONTINUE

```


APPENDIX E

OPERATING DESCRIPTION OF ANALYTICAL ERROR DETECTION PROGRAMS

The analytic error detection model has been implemented as two FORTRAN programs, TRAV and EXP. Given a directed graph representation of a computer program with a unique start node and a unique exit node, branch probabilities and the expected number of errors on each arc, the programs compute the expected number of errors detected by each of a sequence of inputs that begin at the start node and end at the exit node. For example, for the program represented by Figure 1 with the indicated branch probabilities and the expected number of errors for each arc of 0.6, the output of program EXP is the table of Figure 2 and the graph of Figure 3.

The analysis assumes that an input is made at the start node, the arcs of the graph are traversed with the choice of arc at each branch node made according to the branch probabilities (which should sum to one for each branch node) and the input stops when it reaches the exit node. If an arc is traversed by an input, it is assumed that all the errors on that arc are detected and immediately corrected with no new errors introduced.

The error detection table and graph (for example, Figures 2 and 3) indicate how easy or difficult it is to detect errors in the computer program that is represented by the graph. It is possible to see how the error detection process is affected by different error distributions and it is possible to get some idea of when to stop testing for a given distribution of errors.

The computation is divided into two programs; the first computes the traversal probabilities for the graph--this is done only once for each graph. The second program uses the output of the first program plus an estimate of the expected number of errors on each arc to compute the expected number of errors detected. Typical use involves using the second program repeatedly with

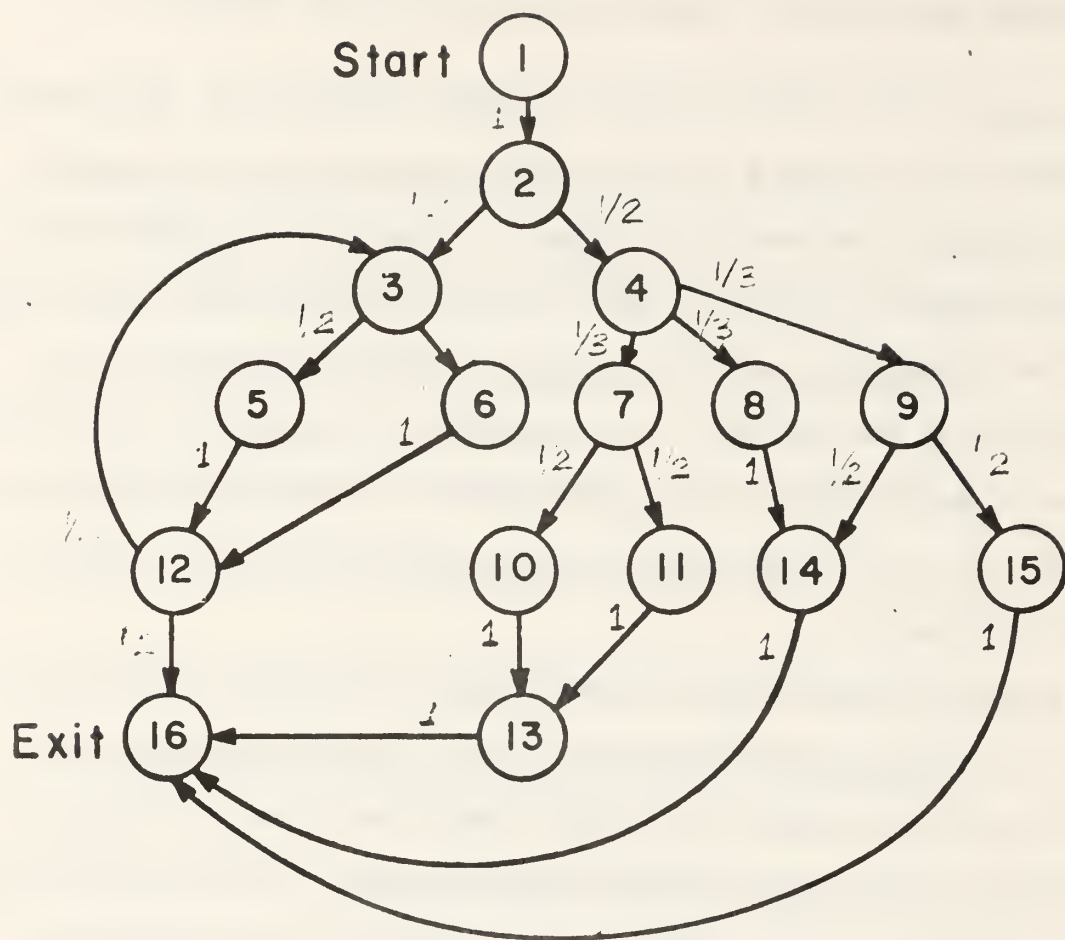


Figure 1

EXPECTED NUMBER OF ERRORS DETECTED VERSION 1.0

PROGRAM TITLE: ERROR DETECTION MODEL FIGURE 1

INPUTS = 20

NUMBER OF ARCS = 22

TAIL	ARC HEAD	BRANCH PROB.	TRAVERSAL PROB.	EXPECTED NUMBER OF ERRORS
6	12	1.0000	0.3333	0.60
12	3	0.5000	0.2500	0.60
12	16	0.5000	0.5000	0.60
11	13	1.0000	0.0833	0.60
13	16	1.0000	0.1667	0.60
14	16	1.0000	0.2500	0.60
7	11	0.5000	0.0833	0.60
8	14	1.0000	0.1667	0.60
1	2	1.0000	1.0000	0.60
2	3	0.5000	0.5000	0.60
2	4	0.5000	0.5000	0.60
4	7	0.3333	0.1667	0.60
4	8	0.3333	0.1667	0.60
4	9	0.3333	0.1667	0.60
7	10	0.5000	0.0833	0.60
9	14	0.5000	0.0833	0.60
9	15	0.5000	0.0833	0.60
10	13	1.0000	0.0833	0.60
15	16	1.0000	0.0833	0.60
3	5	0.5000	0.3333	0.60
3	6	0.5000	0.3333	0.60
5	12	1.0000	0.3333	0.60

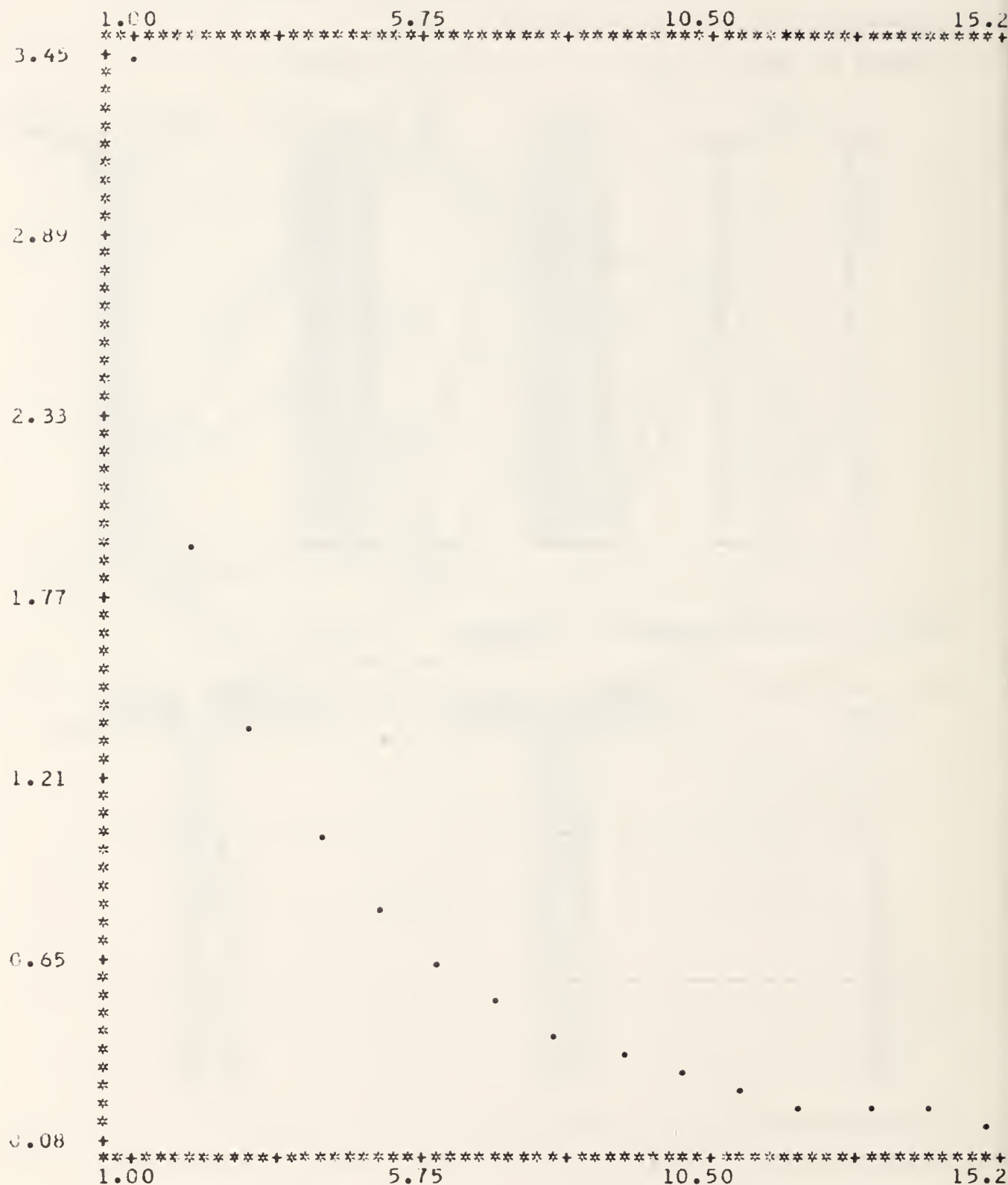
INITIAL EXPECTED NUMBER OF ERRORS= 13.20

INPUT	EXPECTED NUMBER OF ERRORS DETECTED	CUMMULATIVE EXPECTED NUMBER OF ERRORS DETECTED
1	3.45	3.45
2	1.95	5.40
3	1.39	6.79
4	1.04	7.82
5	0.80	8.62
6	0.63	9.25
7	0.51	9.76
8	0.42	10.19
9	0.36	10.54
10	0.30	10.85
11	0.26	11.10
12	0.22	11.33
13	0.20	11.52
14	0.17	11.69
15	0.15	11.84
16	0.13	11.98
17	0.12	12.10
18	0.11	12.20
19	0.09	12.30
20	0.08	12.38

Figure 2

GRAPH OF EXPECTED NUMBER OF ERRORS DETECTED -VS- NUMBER OF INPUTS.

PROGRAM TITLE: ERROR DETECTION MODEL FIGURE 1



X-SCALE: "*" = 0.237E 00 UNITS

Y-SCALE: "*" = 0.561E-01 UNITS

INPUT NUMBER

Figure 3

different error estimates. The compute time and storage requirements for the first program is many times that for the second program.

Program Trav

The first program, TRAV, computes for each arc the probability that an input beginning at the start node will traverse the arc. Since the first time an arc is traversed all errors are detected and corrected, it is not of interest if the arc is traversed one time or many times by a single input; thus the traversal probability is the probability of traversing the arc one or more times.

It is necessary that the user identify the arcs that can be traversed more than once by a given input; these arcs, called "repeated" arcs, must be treated differently in the computation. In the example, because arc $12 \rightarrow 3$ loops back, arcs $3 \rightarrow 5$, $5 \rightarrow 12$, $3 \rightarrow 6$, $6 \rightarrow 12$ and $12 \rightarrow 3$ are repeated arcs. (They are the only repeated arcs in Figure 1.) If a repeated arc is not identified by the user, the traversal probability will be wrong (too high). The traversal probability of a non-repeated arc that is erroneously identified as a repeated arc will be correct. However, since the calculation for repeated arcs involves inverting a matrix it saves computer time to correctly identify the repeated arcs.

For non-repeating arcs, the computation of the traversal probability is easy: The probability of reaching any node is the sum of the traversal probabilities of arcs coming into that node. The traversal probability of arcs leaving a node is the branch probability of that arc times the probability of reaching the node. For repeating arcs the calculation is more complex; for example, in Figure 1 the probability of reaching node 3 is $1/2$ but the probability of traversing arc $3 \rightarrow 5$ is greater than $1/4$ because even if an input traverses arc $3 \rightarrow 6$ there is some chance that node 3 will be revisited via arc $12 \rightarrow 3$ and arc $3 \rightarrow 5$ then traversed. The probability of traversing arcs $3 \rightarrow 6$, $6 \rightarrow 12$ and $12 \rightarrow 3$ and then traversing $3 \rightarrow 5$ for the first

time is $1/4 \cdot (1/2) \cdot (1/2) = 1/16$. The probability of traversing arc $3 \rightarrow 6$ twice then traversing arc $3 \rightarrow 5$ is $1/16(1/2)1/2 = 1/64$. Thus the traversal probability of arc $3 \rightarrow 5$ is $1/4 + 1/16 + 1/64 + \dots = 1/3$. Program TRAV computes the traversal probability by means of a Markov chain analysis.

The input to program TRAV is the directed graph and its branch probabilities. Each arc is input giving its tail node, its head node, its branch probability (i.e. probability of traversing the arc given you are at its tail node) and an indication if it is a repeated arc. Also input is the start and exit node numbers. The node numbers can be any integers between 01 and 99. There may be multiple arcs between the same two nodes. Since the sum of the branch probabilities from any node should equal one, the program checks for this. There should be no arcs branching from the exit node; the program checks for this also. The arcs can be input in any order.

Input format for program TRAV:

Card 1. (20A4) Alphanumeric title card.

Card 2. (1X,I2,1X,I2) Start node number and exit node number

Card 3 etc. (1X,I2,1X,I2,1X,A1,2X,F 10.5) for each arc of the graph, tail node number, head node number, alpha character 'R' indicates that the arc may be repeated, branch probability which is the probability that the arc will be traversed if you are at its tail node.

Last card. 00 or blanks in columns 2 and 3.

The output of the program is a printed and punched description of each arc with its branch and traversal probability. The punch output is ready (with some additions described below) for input to the second program.

Punch output of program TRAV:

Card 1. Title card

Card 2. Card to insert no. of inputs for expected errors program.

Card 3 etc. Same as input except for traversal probabilities added (F10.5) in columns 21 to 30.

Last card. 00 in columns 2 and 3.

Program TRAV is presently limited to 99 arcs. To accommodate more it is necessary to change "IDIM" and the arrays indicated in the comments cards of program TRAV and its subroutine MARKOV.

Data checks are made on the input and output:

Input check no. 1. Input format forces node numbers to be less than 100.

Input check no. 2. Check for input limit of 'IDIM' arcs.

Input check no. 3. Exit node should have no arcs branching away from it.

Input check no. 4. No branch probability should be less than zero or greater than one.

Input check no. 5. Check if there exist paths from start node that do not reach exit node.

Input check no. 6. Check that sum of branch probabilities from all nodes equal approximately one. If it does not, print warning and then divide by sum to make it equal to one.

Input check no 7. Check that start node is the tail of some arc and that exit node is the head of some arc.

The storage required depends on the number of arcs squared and the calculation of repeated arcs involves the inversion of a matrix that has a row for each arc. Thus storage and computer time can be reduced by decomposing a graph. For example, Figure 1 can be decomposed into two graphs, one with arcs $3 \rightarrow 5$, $3 \rightarrow 6$, $5 \rightarrow 12$, $6 \rightarrow 12$, $12 \rightarrow 16$ and $12 \rightarrow 3$ replaced by an arc $3 \rightarrow 16$ with branch probability 1 and the other with arcs $1 \rightarrow 2$, $2 \rightarrow 3$, $3 \rightarrow 5$, $3 \rightarrow 6$, $6 \rightarrow 12$, $5 \rightarrow 12$, $12 \rightarrow 3$, $12 \rightarrow 16$ and an arc $2 \rightarrow 16$ with branch probability $1/2$. The results of two applications of program TRAV can be combined to give the results for the original graph.

Computer time can also be saved by analyzing the graph before using the program. For example, in Figure 1, it is clear that the traversal probability of arcs $3 \rightarrow 6$, $3 \rightarrow 5$, $6 \rightarrow 12$ and $5 \rightarrow 12$ are equal. Thus only one need be marked "R" in the input (saving 3 inversions); the punch output can then be changed to correct the values for the 3 arcs without an "R."

Program EXP

The second program, EXP, computes the expected number of errors detected for a sequence of inputs. The input is the punched card output of the TRAV program, the expected number of errors for each arc and the number of inputs. The output is figures 2 and 3.

The calculation of the expected number of errors detected (and corrected) is straightforward. Let p_j be the traversal probability for arc j computed by the TRAV program and μ_j be the expected number of errors. The expected number of errors detected by the first input is $\sum p_j \mu_j$ where the summation is over all the arcs of the graph. After the first input the expected number of errors in arc j is $\mu_{j2} = \mu_j(1-p_j)$ (where the 2 indicates this is the expected number of errors before the second input). The expected number of errors detected by the second input is $\sum \mu_{j2} p_j$. In general, for the k^{th} input the expected number of errors is $\sum \mu_{jk} p_j$ where $\mu_{jk} = \mu_j(1-p)^{k-1}$.

Input format for program EXP:

Card 1. Title card output from traversal program.

Card 2. (I3) Number of inputs to the directed graph.

Card 3 etc. Traversal probability output from traversal program.

Card N. Final traversal card, 00 or blank in columns 2 and 3 output from traversal program.

Card N+1 etc. (8F10.2) Expected number of errors for each arc. Ordering same as traversal probability input above.

Last card. No final card is necessary.

The output is a table and a graph of the expected number of errors detected and a graph of the cumulative number of errors detected.

Program EXP is currently limited to 99 arcs just as program TRAV. It is also limited to 150 inputs, to accommodate more inputs it is necessary to change "LIMIT" and the arrays indicated in the comments cards of program EXP.

The graphs are produced by two FORTRAN subroutines developed by the NPS computer staff.

Data checks are made on input:

Input check no. 1. Check if number of inputs is less than 'limit'.

Input check no. 2. Check if expected number of errors is nonnegative.

The listings and sample input and output are attached.

```

*****
**
** TRAVSAL PROGRAM TO COMPUTE THE TRAVERSAL
** PROBABILITIES OF A DIRECTED GRAPH FOR INPUTS BEGINNING
** AT THE START NODE AND ENDING AT THE EXIT NODE.
**
** VERSION 1.0 JUNE 1975.
**
** GCRDCN F. BRADLEY
** OPERATIONS RESEARCH DEPARTMENT
** NAVAL POSTGRADUATE SCHOOL
** MCINTIREY, CALIFORNIA 94340
** PHONE 408-646-2769 AUTOVON 479-2769
** PHONE 408-646-2471 AUTOVON 479-2471
**
** INPUT 1. (20A4) ALPHANUMERIC TITLE CARD.
** CARD 1. 1X,12,1X,12,1 START NODE NUMBER AND EXIT NODE
** CARD 2. NUMBER
** CARD 3. (1X,12,1X,12,1X,A1,2X,F10.5) FOR EACH ARC OF
** THE GRAPH, TAIL NODE NUMBER, HEAD NODE NUMBER,
** ALPHA CHARACTER 'R' INDICATES THAT THE ARC MAY BE
** REPEATED, BRANCH PROBABILITY WHICH IS THE PROB.
** THAT THE ARC WILL BE TRAVERSED IF YOU ARE AT ITS
** TAIL NODE.
** LAST CARD. 00 OR BLANKS IN COLUMNS 2 AND 3.
**
** ANY ARC THAT MAY BE TRAVERSED MORE THAN ONCE BY ANY PATH
** FROM THE START NODE TO THE EXIT NODE SHOULD BE MARKED
** WITH AN 'R' IN COLUMN 8 TO ASSURE THE CORRECT TRAVERSAL
** PROBABILITY.
**
** PUNCH OUTPUT FOR EXPECTED ERRORS PROGRAM.
** CARD 1. TITLE CARD
** CARD 2. CARD TO INSERT NU. OF INPUTS FOR EXPECTED ERRORS
** PROGRAM.
** CARD 3. ETC. SAME AS INPUT EXCEPT FOR TRAVERSAL
** PROBABILITIES ADDED (F10.5) IN COLUMNS 21 TO 30.
** LAST CARD. 00 IN COLUMNS 2 AND 3.

```

TRAVC010
 TRAVC020
 TRAVC030
 TRAVC040
 TRAVC050
 TRAVC060
 TRAVC070
 TRAVC080
 TRAVC090
 TRAVC100
 TRAVC110
 TRAVC120
 TRAVC130
 TRAVC140
 TRAVC150
 TRAVC160
 TRAVC170
 TRAVC180
 TRAVC190
 TRAVC200
 TRAVC210
 TRAVC220
 TRAVC230
 TRAVC240
 TRAVC250
 TRAVC260
 TRAVC270
 TRAVC280
 TRAVC290
 TRAVC300
 TRAVC310
 TRAVC320
 TRAVC330
 TRAVC340
 TRAVC350
 TRAVC360
 TRAVC370
 TRAVC380
 TRAVC390


```

DATA RLEI/1HR/
INTEGER CRRER
C IDIM MUST BE SET EQUAL TO DIMENSION OF P,T,X,IST MINUS ONE.
IDIM = 99
C
C READ AND PRINT TITLE OF GRAPH.
C
1 WRITE(6,860)
READ(5,310) (TITLE(I), I=1,20)
WRITE(6,820) (TITLE(I), I=1,20)
C
C READ AND PRINT NUMBER OF START AND EXIT NODES.
C
READ(5,330) ISTART, IEXIT
WRITE(6,840) ISTART, IEXIT
C
C READ IN AND COUNT ARCS
C
N = 0
20 N = N + 1
C * INPUT CHECK NO. 2. CHECK FOR INPUT LIMIT OF 'IDIM' ARCS.
IF(N.LE.IDIM+1) GO TO 30
WRITE(6,530) IDIM
STOP
30 PEAC(5,850) ITAIL(1), IHEAD(N), REP(N), BRAN(N)
IF(ITAIL(N).NE.0) GO TO 20
N = N - 1
C
C * INPUT CHECK NO. 4. NO BRANCH PROBABILITY SHOULD BE LESS
C * THAN ZERO OR GREATER THAN ONE.
C * INPUT CHECK NO. 3. EXIT NODE SHOULD HAVE NO ARCS BRANCHING
C * AWAY FROM IT.

```

TRAV0740
 TRAV0750
 TRAV0760
 TRAV0770
 TRAV0780
 TRAV0790
 TRAV0800
 TRAV0810
 TRAV0820
 TRAV0830
 TRAV0840
 TRAV0850
 TRAV0860
 TRAV0870
 TRAV0880
 TRAV0890
 TRAV0900
 TRAV0910
 TRAV0920
 TRAV0930
 TRAV0940
 TRAV0950
 TRAV0960
 TRAV0970
 TRAV0980
 TRAV0990
 TRAV1000
 TRAV1010
 TRAV1020
 TRAV1030
 TRAV1040
 TRAV1050
 TRAV1060
 TRAV1070

	DATA RLET/1HR/ INTEGER GREER		TRAV0740
			TRAV0750
C	IDIM MUST BE SET EQUAL TO DIMENSION OF P,T,X,IST	MINUS ONE.	TRAV0760
	IDIM = 99		TRAV0770
C			TRAV0780
C			TRAV0790
C	READ AND PRINT TITLE OF GRAPH.		TRAV0800
	1 WRITE(6,800)		TRAV0810
	READ(5,310) (TITLE(I), I=1,20)		TRAV0820
	WRITE(6,820) (TITLE(I), I=1,20)		TRAV0830
C			TRAV0840
C	READ AND PRINT NUMBER OF START AND EXIT NODES.		TRAV0850
	READ(5,330) ISTART, IEXIT		TRAV0860
	WRITE(6,840) ISTART, IEXIT		TRAV0870
C			TRAV0880
C	READ IN AND COUNT ARCS		TRAV0890
	N=C		TRAV0900
	20 N = N + 1		TRAV0910
C	* INPUT CHECK NO. 2. CHECK FOR INPUT LIMIT OF 'IDIM' ARCS.		TRAV0920
	IF (I.LE. IDIM+1) GO TO 30		TRAV0930
	WRITE(6,930) IDIM		TRAV0940
	Stop		TRAV0950
	30 PEAC(5,850) ITAIL(1), IHEAD(N), REP(N), BRAN(N)		TRAV0960
	IF (ITAIL(N).NE.0) GO TO 20		TRAV0970
	I = N - 1		TRAV0980
C	* INPUT CHECK NO. 4. NO BRANCH PROBABILITY SHOULD BE LESS		TRAV0990
	THAN ZERO OR GREATER THAN ONE.		TRAV1000
C	* INPUT CHECK NO. 3. EXIT NODE SHOULD HAVE NO ARCS BRANCHING		TRAV1010
	AWAY FROM IT.		TRAV1020
C			TRAV1030
C			TRAV1040
C			TRAV1050
C			TRAV1060
C			TRAV1070


```

C
DC 50 I = 1, N
IF (BRAN(I).GE.C.O.AND.BRAN(I).LE.1.0) GO TO 40
WRITE(6,940) I, BRAN(I)
STOP
40 IF (ITAIL(I).EQ.IEXIT) WRITE(6,950) I
50 CONTINUE

C
C * INPUT CHECK NO. 7. CHECK THAT START NODE IS THE TAIL
C * OF SOME ARC AND THAT EXIT NODE IS THE HEAD OF SOME
C * ARC.
C
DC 60 I = 1, N
IF (IHEAD(I).EQ.IEXIT) GO TO 70
60 CONTINUE
WRITE(6,970)
STOP
70 DC 80 I = 1, N
IF (ITAIL(I).EQ.ISTART) GO TO 90
80 CONTINUE
WRITE(6,980)
STOP

C PRINT NUMBER OF ARCS.
C
90 WRITE(6,960) N
CRDER = N + 1

C INITIALIZE PHONY FINAL STATE.
C
ITAIL(CRDER) = IEXIT
IHEAD(CRDER) = 9999
BRAN(CRDER) = 1.0

C SET UP TRANSITION MATRIX.
C
DO 120 I = 1, N
SUM = 0.0
DO 100 J = 1, CRDER

```

```

TRAVI080
TRAVI090
TRAVI100
TRAVI110
TRAVI120
TRAVI130
TRAVI140
TRAVI150
TRAVI160
TRAVI170
TRAVI180
TRAVI190
TRAVI200
TRAVI210
TRAVI220
TRAVI230
TRAVI240
TRAVI250
TRAVI260
TRAVI270
TRAVI280
TRAVI290
TRAVI300
TRAVI310
TRAVI320
TRAVI330
TRAVI340
TRAVI350
TRAVI360
TRAVI370
TRAVI380
TRAVI390
TRAVI400
TRAVI410
TRAVI420
TRAVI430
TRAVI440
TRAVI450
TRAVI460

```

```

P(I,J) = 0.0
IF(IHEAD(I).NE. I) GO TO 100
P(I,J) = BRAN(J)
SUM = SUM + BRAN(J)
100 CONTINUE
      * INPUT CHECK NO. 6. CHECK THAT SUM OF BRANCH PROBABILITIES
      * FROM ALL NODES EQUAL APPROXIMATELY
      * CNE. IF IT DOES NOT, PRINT WARNING AND THEN DIVIDE
      * BY SUM TO MAKE IT EQUAL TO ONE.
      * IF(SUM.GT.1.005.OR.SUM.LT.0.995) WRITE(6,900)IHEAD(I),SUM
      * DIVIDE THROUGH BY SUM SO THAT ROW SUM IS 1.0
110 DO 120 J = 1,ORDER
120 P(I,J) = P(I,J)/SUM
130 CONTINUE
      * SET UP PCW FOR PHONY FINAL STATE.
      * DO 140 J = 1,ORDER
140 P(ORDER,J) = 0.0
      * CALL MARKUV SUBROUTINE.
      * CALL MARKUV(ORDER)
      * COMPUTE INITIAL PROBABILITIES OF BEGINNING ARGS.
      * SUM = 0.0
      * DO 150 I = 1,ORDER
      * Z(I) = 0.0
      * IF(I) I) .EQ. I) START) Z(I) = BRAN(I)
      * SUM = SUM + Z(I)
      * INPUT CHECK NO. 6. CHECK THAT SUM OF BRANCH PROBABILITIES
      * FROM ALL NODES EQUAL APPROXIMATELY
      * CNE. IF IT DOES NOT, PRINT WARNING AND THEN DIVIDE
      * BY SUM TO MAKE IT EQUAL TO ONE.

```

```

TRAV1470
TRAV1480
TRAV1490
TRAV1500
TRAV1510
TRAV1520
TRAV1530
TRAV1540
TRAV1550
TRAV1560
TRAV1570
TRAV1580
TRAV1590
TRAV1600
TRAV1610
TRAV1620
TRAV1630
TRAV1640
TRAV1650
TRAV1660
TRAV1670
TRAV1680
TRAV1690
TRAV1700
TRAV1710
TRAV1720
TRAV1730
TRAV1740
TRAV1750
TRAV1760
TRAV1770
TRAV1780
TRAV1790
TRAV1800
TRAV1810
TRAV1820
TRAV1830

```



```

SUBROUTINE MARKUV(ORDER)
C ORIGINALLY WRITTEN FOR CDC 6600, CONVERTED TO 360/67 4 NOV 74
C NO GUARANTEES OF PERFORMANCE - G. BROWN, NPS, 93940
COMMON P(100,100), T(100,100), X(100,100), IST(100)
DIMENSION IB(100)
INTEGER ORDER

C IDIM MUST BE SET EQUAL TO DIMENSION OF P,T,X,IST,IB
ICIM = 100

C
C DET = 0.0
C IDENTIFY IDENTITY PART OF MATRIX
NB = 1
DO 100 I=1,ORDER
IF ( P(I,I) ) .NE. 1.0 ) GO TO 100
IB(NB) = 1
NB = NB + 1
100 CONTINUE

C K = NB - 1
C INDICATE REORDERING FOR NON IDENTITY PART.
DO 110 I = 1,CRDER
DO 105 J=1,K
IF ( IB(J) ) .EQ. 1 ) GO TO 110
105 CONTINUE
IB(NB) = 1
NB = NB + 1
110 CONTINUE
C MOVE P(I,J) TO T(I,J) REORDERING ROWS AND COLUMNS.
DO 120 I=1,CRDER
II = IB(I)
DO 120 J=1,CRDER
JJ = IB(J)
T(J,II) = P(II,JJ)
120 CONTINUE

```

MARK0010
 MARK0020
 MARK0030
 MARK0040
 MARK0050
 MARK0060
 MARK0070
 MARK0080
 MARK0090
 MARK0100
 MARK0110
 MARK0120
 MARK0130
 MARK0140
 MARK0150
 MARK0160
 MARK0170
 MARK0180
 MARK0190
 MARK0200
 MARK0210
 MARK0220
 MARK0230
 MARK0240
 MARK0250
 MARK0260
 MARK0270
 MARK0280
 MARK0290
 MARK0300
 MARK0310
 MARK0320
 MARK0330
 MARK0340

```

L = K + 1
DO 200 I=L,CRDER
  IK = I-K
  II = IB(I)
DO 190 J=L,CRDER
  JK = J - K
  JJ = IB(J)
  T(IK,JK) = P(II,JJ)
190 CONTINUE
  T(IK,IK) = T(IK,IK) + 1.0
200 CONTINUE
C CALL INVERT FOR NON IDENTITY PART OF MATRIX.
M = CRDER - K
I = ISOLVE(ICIM,M,-M,T,X,DET,IST)
C IF MATRIX IS NONSINGULAR, PRINT MESSAGE.
IF(I.EQ.1) WRITE(6,834)
834 FCMMAT(30HIMATRIX SINGULAR, CHECK INPUT, )
FOR DEBUG PURPOSES, PRINT ORIGINAL AND NONIDENTITY INVERSE.
C
C 60 FCMMAT( 28HORIGINAL TRANSITION MATRIX. )
DO 90 I = 1,ORDER
  PRINT 81, (P(I,J),J=1,ORDER)
  PRINT 82, (IB(J),J=L,CRDER)
DC 220 I=1,M
  J = I + K
  PRINT 141, IB(J)
  PRINT 31, (X(I,J),J=1,M)
220 CONTINUE
32 FCMMAT( 54FINVERSE OF NONIDENTITY PART WITH CORRESPONDING STATES
  (2X,10F10.7) )
141 FCMMAT(1H //, )
81 FCMMAT( 5X, 10F10.7, /, (5X, 10F10.7) )
RETURN
END

```

MARK0350
 MARK0360
 MARK0370
 MARK0380
 MARK0390
 MARK0400
 MARK0410
 MARK0420
 MARK0430
 MARK0440
 MARK0450
 MARK0460
 MARK0470
 MARK0480
 MARK0490
 MARK0500
 MARK0510
 MARK0520
 MARK0530
 MARK0540
 MARK0550
 MARK0560
 MARK0570
 MARK0580
 MARK0590
 MARK0600
 MARK0610
 MARK0620
 MARK0630
 MARK0640
 MARK0650
 MARK0660
 MARK0670
 MARK0680
 MARK0690


```

      DO I = 1, N
1    IC(I) = I
      IF (INC) 5, 2000, 15
      INVERSE REQUIRED
5    ISUB2 = 0
      DO 10 J = 1, N
      ISUB1 = ISUB2
      DO 6 I = 1, N
      ISUB1 = ISUB1 + I
6    B(ISUB1) = 0
      ISUB1 = ISUB2 + J
      B(ISUB1) = 1
10   ISUB2 = ISUB2 + ID
      START MAIN LOOP
15   DO 100 L = 1, N
      LM1 = L - 1
      DO 40 I = L, N
      PIVOT = 0
      ISUB1 = ID * LM1 + I
      ISUB2 = ISUB1
      DO 20 J = L, N
      IF (ABS(PIVOT) - ABS(A(ISUB1))) 17, 20, 20
17   PIVOT = A(ISUB1)
      JB = J
      ISUB1 = ISUB1 + ID
      COMPUTE DETERMINANT
      DET = DET * PIVOT
      TEST FOR SINGULAR MATRIX
      IF (PIVOT) 24, 2000, 24
24   DO 25 J = L, N
      A(ISUB2) = A(ISUB2) / PIVOT
25   ISUB2 = ISUB2 + ID
      IF (ICV0) 29, 29, 35
29   ISUB1 = I
      DO 30 J = 1, M
      B(ISUB1) = B(ISUB1) / PIVOT
30   ISUB1 = ISUB1 + ID

```

```

ISOL0370
ISOL0380
ISOL0390
ISOL0400
ISOL0410
ISOL0420
ISOL0430
ISOL0440
ISOL0450
ISOL0460
ISOL0470
ISOL0480
ISOL0490
ISOL0500
ISOL0510
ISOL0520
ISOL0530
ISOL0540
ISOL0550
ISOL0560
ISOL0570
ISOL0580
ISOL0590
ISOL0600
ISOL0610
ISOL0620
ISOL0630
ISOL0640
ISOL0650
ISOL0660
ISOL0670
ISOL0680
ISOL0690
ISOL0700
ISOL0710
ISOL0720
ISOL0730

```

```

35 IF (I-L) 40, 39, 40
39 JP = JB
40 CONTINUE
C INTERCHANGE COLUMNS
100 IF (JP-L) 101, 260, 101
101 IF (IDV) 102, 102, 110
102 IT = IC(L)
IC(L) = IC(JP)
IC(JP) = IT
110 IR = ID * LM1
IT = ID * JP - ID
DO 120 I=1,N
ISUB1 = IR + I
ISUB2 = IT + I
S = A(ISUB1)
A(ISUB1) = A(ISUB2)
A(ISUB2) = S
120 DET = DET * S
C REDUCE PIVOT COLUMN
IR = IC * LM1
DO 400 I=1,N
IR = IR + I
PIVOT = A(IR)
IF (I-L) 261, 400, 261
261 IF (PIVOT) 270, 400, 270
270 ISUB1 = I
ISUB2 = I
DO 360 J=1,N
IF (J-L) 300, 300, 280
S = PIVOT * A(ISUB1)
A(ISUB2) = A(ISUB2) - S
290 IF (ABS(A(ISUB2))) - ABS(3.E-10 * S) 290, 300, 300
300 A(ISUB2) = 0.
310 IF (J-L) 310, 310, 350
320 R(ISUB2) = B(ISUB2) - PIVOT * B(ISUB1)
330 ISUB1 = ISUB1 + ID
350 ISUB2 = ISUB2 + ID
400 CONTINUE
1000 IF (ICV) 1100, 1100, 1500
C REARRANGE VARIABLES
1100 DO 1200 I=1,N
ISUB1 = IC(L)
ISUB2 = I
DO 1200 J=1,M
A(ISUB1) = B(ISUB2)
ISUB1 = ISUB1 + ID
ISUB2 = ISUB2 + ID
1200 RETURN
C SINGULAR MATRIX
1500 SINGULAR = 1
2000 GO TO 1507
END

```

ERROR DETECTION MODEL FIGURE 1

S01E16		
A06-12	P	1.0
A12-03	P	.5
A12-16		.5
A11-13		1.0
A13-16		1.0
A14-16		1.0
AC7-11		.5
AC8-14		1.0
AO1-02		1.0
AO2-03		.5
AC2-04		.5
AO4-07		.3333
AC4-C8		.3333
AO4-09		.3333
AC7-10		.5
AC9-14		.5
AC9-15		.5
A10-13		1.0
A15-16		1.0
AC5-05	F	.5
AO3-C6	P	.5
AO5-12	P	1.0
000		

Card input to program TRAV

PROGRAM TITLE: ERROR DETECTION MODEL FIGURE 1

START NODE = 1 EXIT NODE = 16

NUMBER OF ARCS = 22

TAIL	ARC	HEAD	REPEAT	BRANCH PROB.	TRAVERSAL PROB.
6		12	R	1.0000	0.3333
12		3	R	0.5000	0.2500
11		13		1.0000	0.0833
13		16		1.0000	0.1667
14		16		1.0000	0.2500
7		11		0.5000	0.0833
8		14		1.0000	0.1667
1		2		1.0000	1.0000
2		3		0.5000	0.5000
12		16		0.5000	0.5000
2		4		0.5000	0.5000
4		7		0.3333	0.1667
4		8		0.3333	0.1667
4		9		0.3333	0.1667
7		10		0.5000	0.0833
9		14		0.5000	0.0833
9		15		0.5000	0.0833
10		13		1.0000	0.0833
15		16		1.0000	0.0833
3		5	R	0.5000	0.3333
3		6	R	0.5000	0.3333
5		12	R	1.0000	0.3333

Printed output of program TRAV

ERROR DETECTION MODEL FIGURE 1
INPUTS

6	12	R	1.00000	0.33333
12	3	R	0.50000	0.25000
12	16		0.50000	0.50000
11	13		1.00000	0.08333
13	16		1.00000	0.16667
14	16		1.00000	0.25000
7	11		0.50000	0.08333
8	14		1.00000	0.16667
1	2		1.00000	1.00000
2	3		0.50000	0.50000
2	4		0.50000	0.50000
4	7		0.33333	0.16667
4	8		0.33333	0.16667
4	9		0.33333	0.16667
7	10		0.50000	0.08333
9	14		0.50000	0.08333
9	15		0.50000	0.08333
10	13		1.00000	0.08333
15	16		1.00000	0.08333
3	5	R	0.50000	0.33333
3	6	R	0.50000	0.33333
5	12	R	1.00000	0.33333

000

Card output from program TRAV


```

*****
** PROGRAM TO COMPUTE EXPECTED AND CUMULATIVE NUMBER OF
** ERRORS DETECTED AND OUTPUT TABLE AND GRAPH OF THE RESULT.
**
** VERSION 1.0 JUNE 1975.
**
** GORDON H. BRADLEY
** OPERATIONS RESEARCH DEPARTMENT
** NAVAL POSTGRADUATE SCHOOL
** MCNTREY, CALIFORNIA 94340
** PHONE 408-646-2769 AUTOVON 479-2769
** PHONE 408-646-2471 AUTOVON 479-2471
**
** INPUT.
** CARD 1. TITLE CARD OUTPUT FROM TRAVERSAL PROGRAM.
** CARD 2. (I3) NUMBER OF INPUTS TO THE DIRECTED GRAPH.
** CARD 3. ETC. TRAVERSAL PROB. OUTPUT FROM TRAVERSAL PROGRAM.
** CARD N. FINAL TRAVERSAL CARD, 00 OR BLANK IN COLUMNS 2 AND 3
** CARD N+1 ETC. (8F10.2) EXPECTED NUMBER OF ERRORS FOR EACH
** LAST ARC. ORDERING SAME AS TRAVERSAL PROB. INPUT ABOVE.
** LAST CARD. NO FINAL CARD IS NECESSARY.
**
** TO HANDLE TWO OR MORE GRAPHS BRANCH FROM END OF PROGRAM
** 'STOP' TO STATEMENT 1.
** TO HANDLE TWO OR MORE EXPECTED ERROR DISTRIBUTIONS FOR A
** GIVEN GRAPH, BRANCH FROM END OF PROGRAM 'STOP' TO
** STATEMENT 2.
**
** ASSUMES INPUT OF ARCS IS CORRECT SINCE PREVIOUS PROGRAM
** HAD REASONABLENESS CHECKS.
** INPUT CHECK NO. 1. CHECK IF NUMBER OF INPUTS IS LESS
** INPUT THAN 'LIMIT'.
** INPUT CHECK NO. 2. CHECK IF EXPECTED NUMBER OF ERRORS
** IS NON-NEGATIVE.
**
** NOTE. 'LIMIT' IS THE DIMENSION OF E, CUM AND X. DIMENSION
** OF ITAIL, IHEAD, BRAN, TRAV, AND MU IS ASSUMED LARGE
** ENOUGH TO HANDLE ANY INPUT.
**
** ASSUMES SUBROUTINE PLOTP WHICH IN TURN ASSUMES SUBROUTINE
** UTPLT. THESE SUBROUTINES ARE USED FOR THE OUTPUT
** OF THE GRAPHS ONLY.
*****

```

EXP 0010
EXP 0020
EXP 0030
EXP 0040
EXP 0050
EXP 0060
EXP 0070
EXP 0080
EXP 0090
EXP 0100
EXP 0110
EXP 0120
EXP 0130
EXP 0140
EXP 0150
EXP 0160
EXP 0170
EXP 0180
EXP 0190
EXP 0200
EXP 0210
EXP 0220
EXP 0230
EXP 0240
EXP 0250
EXP 0260
EXP 0270
EXP 0280
EXP 0290
EXP 0300
EXP 0310
EXP 0320
EXP 0330
EXP 0340
EXP 0350
EXP 0360
EXP 0370
EXP 0380
EXP 0390
EXP 0400
EXP 0410
EXP 0420
EXP 0430
EXP 0440
EXP 0450
EXP 0460
EXP 0470

```

C      DIMENSION ITAIL(100),IHEAD(100),      BRAN(100),TRAV(100),
C      1 MU(100),TITLE(20),E(150),CUM(150),X(150)
C      REAL MU
C      LIMIT MUST EQUAL DIMENSION OF E,CUM,X
C      LIMIT = 150
C      READ AND PRINT TITLE OF GRAPH.
C
C      1 WRITE(6,800)
C      READ(5,810)(TITLE(I),I=1,20)
C      WRITE(6,820)(TITLE(I),I=1,20)
C      READ AND PRINT NUMBER OF INPUTS.
C
C      READ(5,830) INPUTS
C      * INPUT CHECK NO. 1. CHECK IF NUMBER OF INPUTS IS LESS
C      * THAN LIMIT.
C      IF (INPUTS.LE.LIMIT) GO TO 10
C      WRITE(6,940) LIMIT
C      INPUTS = LIMIT
C      10 WRITE(6,840) INPUTS
C      READ IN AND COUNT NUMBER OF ARCS AND TRAVERSAL PROBABILITIES.
C

```

EXP 0480
EXP 0490
EXP 0500
EXP 0510
EXP 0520
EXP 0530
EXP 0540
EXP 0550
EXP 0560
EXP 0570
EXP 0580
EXP 0590
EXP 0600
EXP 0610
EXP 0620
EXP 0630
EXP 0640
EXP 0650
EXP 0660
EXP 0670
EXP 0680
EXP 0690
EXP 0700
EXP 0710
EXP 0720
EXP 0730

```

C      N=0
C      20 N = N + 1
C      READ(5,850) ITAIL(N),IHEAD(N),      BRAN(N),TRAV(N)
C      IF (ITAIL(N).NE.0) GO TO 20
C      N = N - 1
C      WRITE(6,860) N
C      READ IN EXPECTED NUMBER OF ERRORS FOR EACH PC
C
C      2 READ(5,865) ( MU(I), I = 1,N )
C      PRINT OUT INPUT DATA , TRAVERSAL PROBABILITY AND EXPECTED NUMBER
C      OF ERRORS.
C
C      WRITE(6,870)
C      TOTAL = 0.0
C      DO 30 I=1,N
C      TOTAL = TOTAL + MU(I)
C      WRITE(6,880) ITAIL(I),IHEAD(I),      BRAN(I),TRAV(I),MU(I)
C      * INPUT CHECK NO. 2. CHECK IF EXPECTED NUMBER OF ERRORS
C      * IS NONNEGATIVE.
C      IF (MU(I).LT.0.0) WRITE(6,950) MU(I)
C      30 CONTINUE
C      OUTPUT TOTAL EXPECTED NUMBER OF ERRORS.
C
C      WRITE(6,890) TOTAL

```

EXP 0740
EXP 0750
EXP 0760
EXP 0770
EXP 0780
EXP 0790
EXP 0800
EXP 0810
EXP 0820
EXP 0830
EXP 0840
EXP 0850
EXP 0860
EXP 0870
EXP 0880
EXP 0890
EXP 0900
EXP 0910
EXP 0920
EXP 0930
EXP 0940
EXP 0950
EXP 0960
EXP 0970
EXP 0980
EXP 0990
EXP 1000

PLCP0380
 PLOP0390
 PLOP0400
 PLOP0410
 PLOP0420
 PLOP0430
 PLOP0440
 PLOP0450
 PLOP0460
 PLOP0470
 PLOP0480
 PLOP0490
 PLOP0500
 PLOP0510
 PLOP0520
 PLOP0530
 PLOP0540
 PLOP0550
 PLOP0560
 PLOP0570
 PLOP0580
 PLOP0590
 PLOP0600
 PLOP0610
 PLOP0620
 PLOP0630
 PLOP0640
 PLOP0650
 PLOP0660
 PLOP0670
 PLOP0680
 PLOP0690
 PLOP0700
 PLOP0710
 PLOP0720
 PLOP0730

SCALING IS PERFORMED ONLY ON THE FIRST SET OF POINTS (WHEN
 MODCUR IS 0, 1, 4, 5, 8 OR 9.) FOR A MULTIPLE CURVE GRAPH, (WHEN
 THE USER SHOULD CALL THE SUBROUTINE INITIALLY WITH THE LARGEST
 CURVE TO INSURE OPTIMUM SCALING.

PLOTP/DPLTP USES ONE OF THREE OPTIONAL METHODS FOR
 DETERMINING THE APPROPRIATE SCALE FACTORS.

METHOD 1: PLOTP SCANS THE X AND Y ARRAYS TO DETERMINE THE MAXI-
 MUM AND MINIMUM VALUES. SCALE FACTORS ARE CHOSEN SO
 THAT MAXIMUM X AND MINIMUM X ARE SLIGHTLY WITHIN THE
 LEFT AND RIGHT, RESPECTIVELY OF THE GRAPH BOUNDARIES
 AND, SIMILARLY, THAT MAX Y AND MIN Y ARE SLIGHTLY
 BELOW AND ABOVE, RESPECTIVELY, THE GRAPH BOUNDARIES.
 UTPLUT IS THEN CALLED TO PLOT THE GRAPH.

METHOD 1 IS USED WHEN MODCUR = 0, 1, 2, OR 3

METHOD 2: PLOTP DETERMINES THE MAXIMUM AND MINIMUM VALUES OF X
 AND Y AS IN METHOD 1. IF THE MINIMUM IS GREATER THAN
 ZERO, IT IS SET TO ZERO, AND IF THE MAXIMUM IS LESS
 THAN ZERO, IT IS SET TO ZERO. THE MAXIMUM IS THEN
 ROUNDED UP TO THE NEXT HIGHEST VALUE CONTAINED DOWN TO
 SIGNIFICANT FIGURES AND THE MINIMUM IS ROUNDED DOWN TO
 THE NEXT LOWEST VALUE CONTAINED WHICH IS SIGNIFICANT FIGURES.
 A RANGE IS THEN COMPUTED WHICH IS THE DIFFERENCE BE-
 TWEEN THE MAXIMUM AND THE MINIMUM. THE RANGE IS AD-
 JUSTED UNTIL, IN THE X-DIRECTION, IT IS A MULTIPLE OF
 4, AND IN THE Y-DIRECTION, IT IS A MULTIPLE OF 6.
 ROUNDED MAXIMUM AND MINIMUMS ARE THEN USED TO CALL
 SUBROUTINE UTPLUT WHICH PLOTS THE GRAPH. THE AXES AND
 THIS ALGORITHM IS USED TO "RELATIONALIZE" THE AXES AND
 SCALE FACTORS.

METHOD 2 IS USED WHEN MODCUR = 4, 5, 6, OR 7

CC

PLCPC0740
PLCPC0750
PLCPC0760
PLCPC0770
PLCPC0780
PLCPC0790
PLCPC800
PLCPC810
PLCPC820
PLCPC830
PLCPC840
PLCPC850
PLCPC860
PLCPC870
PLCPC880
PLCPC890
PLCPC900
PLCPC910
PLCPC920
PLCPC930
PLCPC940
PLCPC950
PLCPC960
PLCPC970
PLCPC980
PLCPC990
PLCPC1000
PLCPC1010
PLCPC1020
PLCPC1030
PLCPC1040
PLCPC1050
PLCPC1060
PLCPC1070
PLCPC1080
PLCPC1090
PLCPC1100
PLCPC1120

METHOD 3: THIS IS THE SAME AS METHOD 2 EXCEPT WHEN ALL VALUES OF X OR Y ARE POSITIVE OR NEGATIVE (NO ZERO), THE ORIGIN OF X OF Y (RESPECTIVELY) DOES NOT APPEAR ON THE GRAPH.

METHOD 3 IS USED WHEN MODCUR = 8, 9, 10, OR 11

IN EITHER METHOD, EACH PRINT POSITION IN THE X-DIRECTION WILL BE EQUAL TO $(X_{MAX} - X_{MIN}) / 80$. AND EACH PRINT POSITION IN THE Y-DIRECTION WILL BE EQUAL TO $(Y_{MAX} - Y_{MIN}) / 60$.

GRID LABELLING

THE DATA TO BE GRAPHED WILL BE FIT INTO AN 80 COLUMN BY 60 ROW GRID. THE GRID WILL BE LABELLED AS FOLLOWS:

IN THE X DIRECTION (COLUMN-WISE), THERE WILL BE 5 VALUES: THE MAXIMUM, THE MINIMUM, AND 3 INTERMEDIATE EQUALLY SPACED VALUES.

IN THE Y DIRECTION (ROW-WISE) THERE WILL BE 7 VALUES: THE MAXIMUM, THE MINIMUM, AND 5 INTERMEDIATE EQUALLY SPACED VALUES.

IF THE LABELS HAVE A VALUE BETWEEN 1. AND 10×8 , THEY WILL BE PRINTED IN AN F11.2 FORMAT, OTHERWISE THEY WILL BE PRINTED IN A IPE1J.3 FORMAT.

PLOTTING

FOUR CHARACTERS ARE USED FOR PLOTTING CURVES, ".", "+", "*", AND "X". WHEN MORE THAN ONE CURVE APPEARS ON A GRAPH, EACH IS USED IN TURN IN THE ABOVE ORDER. IF MORE THAN 4 CURVES ARE PLOTTED THE ABOVE CYCLE OF CHARACTERS IS REPEATED. IF A NEW CURVE IS TO BE PLACED IN THE PLOTTING GRID WHERE AN OLD CURVE EXISTS, THE NEW CURVE CHARACTER REPLACES THE OLD ONE. IF 3 IDENTICAL CURVES ARE PLOTTED, THEY WILL APPEAR AS ONE CURVE COMPOSED OF "###'S."

CC

MESSAGES

UNDER CERTAIN CIRCUMSTANCES, A PLOT WILL NOT BE OUTPUT AND ONE OF THE FOLLOWING SELF-EXPLANATORY MESSAGES WILL BE PRINTED ON THE STANDARD OUTPUT IN PLACE OF THE PLOT.

THE FOLLOWING MESSAGES ARE PRODUCED BY PLOTP/DPLTP:

"ALL X VALUES 0. OR THE SAME VALUE. CANNOT SETUP PLOT GRID CHECK MAX AND MIN X FOR INITIAL CALL TO PLOTP/DPLTP."

"ALL Y VALUES 0. OR THE SAME VALUE. CANNOT SETUP PLOT GRID CHECK MAX AND MIN Y FOR INITIAL CALL TO PLOTP/DPLTP."

"GRID NOT SETUP WHEN PLOT INITIALIZED. NO PLOT UNTIL GRID PROPERLY SETUP."

THE FOLLOWING MESSAGES ARE PRODUCED BY UTPLOT:

"ALL X VALUES = 0. CANNOT SETUP PLOT GRID. CHECK MAX & MIN X WHEN MODCUR = 0 OR 1."

"ALL Y VALUES = 0. CANNOT SETUP PLOT GRID. CHECK MAX & MIN Y WHEN MODCUR = 0 OR 1."

"GRID NOT SETUP WHEN MODCUR LAST 0 OR 1. NO PLOT UNTIL PROPERLY SETUP."

NOTE

THE USER IS EXPECTED TO PROVIDE THE NECESSARY CARRIAGE CONTROLS TO PLACE THE GRAPH PROPERLY ON THE PAGE. BEFORE CALLING PLOTP THE USER SHOULD ISSUE A PRINT STATEMENT WHICH

PLOP1130
PLOP1140
PLOP1150
PLOP1160
PLOP1170
PLOP1180
PLOP1190
PLOP1200
PLOP1210
PLOP1220
PLOP1230
PLOP1240
PLOP1250
PLOP1260
PLOP1270
PLOP1280
PLOP1290
PLOP1300
PLOP1310
PLOP1320
PLOP1330
PLOP1340
PLOP1350
PLOP1360
PLOP1370
PLOP1380
PLOP1390
PLOP1400
PLOP1410
PLOP1420
PLOP1430
PLOP1440
PLOP1450
PLOP1460

PL OP1470
PL OP1480
PL OP1490
PL OP1500
PL OP1510
PL OP1520
PL OP1530
PL OP1540
PL OP1550
PL OP1560
PL OP1570
PL OP1580
PL OP1590
PL OP1600
PL OP1610
PL OP1620
PL OP1630
PL OP1640
PL OP1650
PL OP1660
PL OP1670
PL OP1680
PL OP1690
PL OP1700
PL OP1710
PL OP1720
PL OP1730
PL OP1740
PL OP1750
PL OP1760
PL OP1770
PL OP1780
PL OP1790
PL OP1800
PL OP1810
PL OP1820
PL OP1830
PL OP1840
PL OP1850
PL OP1860
PL OP1870

```

DO 1 I=1,KDATA,KKZ
IF(X(I).LT.XMAX) GO TO 6
XMAX=X(I)
6 IF(X(I).GT.XMIN) GO TO 7
XMIN=X(I)
7 IF(Y(I).LT.YMAX) GO TO 8
YMAX=Y(I)
8 IF(Y(I).GT.YMIN) GO TO 1
YMIN=Y(I)
1 CONTINUE

IF NOT AUTOSCALE GO TO CALL UTPLT

IF(XMAX.EQ.XMIN) GO TO 887
IF(YMAX.EQ.YMIN) GO TO 889
IF(ISCT.EQ.1) GO TO 5

COMPUTE X-SCALE & NEW XMAX AND XMIN
CALL PSCALE(XMAX,XMIN,4,ISCT)

COMPUTE Y-SCALE & NEW YMAX AND YMIN
CALL PSCALE(YMAX,YMIN,6,ISCT)

PLOT CURVE

5 CALL UTPLCT(X,Y,KN,RANGE,KKZ,MMC)
IF(MMC .EQ.1.OR.MMC .EQ.2) RETURN

PRINT SCALES WHEN LAST CURVE PLOTTED

```

```

XS=(XMAX-XMIN)/80.
YS=(YMAX-YMIN)/60.
WRITE(6,100) XS,YS
100 FORMAT(15X,'X-SCALE: ',E10.3,' UNITS',//
15X,'Y-SCALE: ',E10.3,' UNITS')

RETURN
889 WRITE(6,888)
888 FORMAT(' ALL Y VALUES=0. OR THE SAME VALUE. CANNOT SETUP PLOT GR
10. CHECK MAX AND MIN Y FOR INITIAL CALL TO PLOTP/DPLTP')
JERR=10
RETURN
887 WRITE(6,886)
886 FORMAT(' ALL X VALUES=0. OR THE SAME VALUE. CANNOT SETUP PLOT GR
10. CHECK MAX AND MIN X FOR INITIAL CALL TO PLOTP/DPLTP')
JERR=10
RETURN
885 WRITE(6,884)
884 FORMAT(' GRID NOT SETUP WHEN PLOT INITIALIZED. NO PLOT UNTIL GR
10 PROPERLY SETUP')
RETURN
END

```

PLOP1880
 PLOP1890
 PLOP1900
 PLOP1910
 PLOP1920
 PLOP1930
 PLOP1940
 PLOP1950
 PLOP1960
 PLOP1970
 PLOP1980
 PLOP1990
 PLOP2000
 PLOP2010
 PLOP2020
 PLOP2030
 PLOP2040
 PLOP2050
 PLOP2060
 PLOP2070
 PLOP2080
 PLOP2090
 PLOP2100
 PLOP2110
 PLOP2120
 PLOP2130
 PLOP2140
 PLOP2150
 PLOP2160
 PLOP2170
 PLOP2180
 PLOP2190

PLOP2200
 PLOP2210
 PLOP2220
 PLOP2230
 PLOP2240
 PLOP2250
 PLOP2260
 PLOP2270
 PLOP2280
 PLOP2290
 PLOP2300
 PLOP2310
 PLOP2320
 PLOP2330
 PLOP2340
 PLOP2350
 PLOP2360
 PLOP2370
 PLOP2380
 PLOP2390
 PLOP2400

PLOP2410
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 PLOP2470
 PLOP2480
 PLOP2490
 PLOP2500
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 PLOP2580
 PLOP2590
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 PLOP2620
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 PLOP2720
 PLOP2730
 PLOP2740
 PLOP2750
 PLOP2760
 PLOP2770

```

SUBROUTINE PSCALE(XMAX,XMIN,IDIV,ISCT)
  DIV=IDIV
  ROUND MAXIMUM TO NEXT HIGHEST 2 SIG FIGS
  IF(ISCT.LT.3) XMAX=AMAX1(0.,XMAX)
  CALL ROUND (XMAX,IMX,FMX)
  IF(ABS(XMX).LE.1.E-7) XMX=0.0
  IMX=IMX-1
  FMX=FMX*10.
  3  XMX=FMX*10.**IMX
    IF(XMX.GE.XMAX) GO TO 2
    FMX=FMX+1.
    IMX=FMX
    FMX=IMM
    GO TO 3
  2  ROUND MINIMUM TO NEXT LOWEST 2 SIG FIGS
    IF(ISCT.LT.3) XMIN=AMIN1(0.,XMIN)
    CALL ROUND (XMIN,IMN,FMN)
    IMN=IMN-1
    FMN=FMN*10.
  14 XMA=FMN*10.**IMN
    IF(XMIN.GE.XMN) GO TO 11
    FMA=FMN-1.
    IMN=FMN
    FMN=IMM
    GO TO 14
  11 ROUND MAX 6 MIN TO 1. OR .1 IF RANGE LARGE
    IF(XMN.LE.1.E-7) XMN=0.
    XSC=XMX-XMN
    IM=0
    SM=1.
  9  IF(XSC/DIV.LE.SM) GO TO 12
    IF(XMN).LT.SM.AND.ABS(XMN).GT.0.) XMN=SIGN(SM,XMN)
    IF(ABS(XMX).LT.SM.AND.ABS(XMX).GT.0.) XMX=SIGN(SM,XMX)
  12 IF(IM.GT.0) GO TO 19
    IM=iM+1
    GO TO 9
  
```

```

C      19  ROUND RANGE (MAX-MIN) TO 2 SIG FIGS
        XSC=XMN-XMN
        CALL ROUND (XSC,IS10,FACTX)
C      FIND FACTOR WHICH IS MULTIPLE OF IDIV
        FACTX=FACTX*10.
        OFAC=FACTX
        IS10=IS10-1
        IFX=FACTX
        FACTX=IFX
        20  IF(MOD(IFX,IDIV).EQ.0.AND.FACTX.GE.CFAC) GO TO 10
            IFX=IFX+1
            FACTX=IFX
            GO TO 20
        10  IF (IDIV.GT.4) GO TO 15
            IF X SCALE BETWEEN 8. AND 10., ROUND TO 10.
            FFX=ABS(FACTX/10.)
            IF (FFX.GT.8..AND.FFX.LT.10.) FFX=10.
            IF (FACTX.LT.0.) FFX=-10.
            FACTX=FFX*10.
        15  XSC=FACTX*10.*IS10
            COMPUTE NEW MAX & MIN FROM ROUNDED SCALE
            IF (XM N*XM X.NE.0.) GO TO 4
            IF (XM N.LT.0.) XMIN=-XSC
            IF (XM X.GT.0.) XMAX=XSC
            RETURN
        4  XMAX=XSC+XMN
            XMIN=XMN
            RETURN
        END

```

```

PL OP2780
PL OP2790
PL OP2800
PL OP2810
PL OP2820
PL OP2830
PL OP2840
PL OP2850
PL OP2860
PL OP2870
PL OP2880
PL OP2890
PL OP2900
PL OP2910
PL OP2920
PL OP2930
PL OP2940
PL OP2950
PL OP2960
PL OP2970
PL OP2980
PL OP2990
PL OP3000
PL OP3010
PL OP3020
PL OP3030
PL OP3040
PL OP3050
PL OP3060

```

PLOP3070
 PLOP3080
 PLOP3090
 PLOP3100
 PLOP3110
 PLOP3120
 PLOP3130
 PLOP3140
 PLOP3150
 PLOP3160
 PLOP3170
 PLOP3180
 PLOP3190
 PLOP3200
 PLOP3210
 PLOP3220
 PLOP3230
 PLOP3240
 PLOP3250
 PLOP3260
 PLOP3270
 PLOP3280
 PLOP3290
 PLOP3300
 PLOP3310
 PLOP3320
 PLOP3330
 PLOP3340
 PLOP3350
 PLOP3360
 PLOP3370
 PLOP3380
 PLOP3390
 PLOP3400
 PLOP3410
 PLOP3420
 PLOP3430

```

SUBROUTINE ROUND(ANUM, IS, FACT)
  EXPRESS ANUM IN SCIENTIFIC NOTATION WHERE
    ANUM=FACT*10.**IS WHERE FACT IS BETWEEN 1. AND 9.9

  IF(ANUM.EQ.0.) GO TO 15
  BNUM=ANUM
  IF(BNUM.LT.0.) BNUM=-BNUM
  IS=ALOG(BNUM)*.43429448
  FACT=BNUM/10.**IS
  FIND POWER OF 10
  IDD=-3
  R2=0
  DO 10 I=1,5
    IDC=IDD+1
    R1=R2
    R2=10.** (IDD+1)
    IF(FACT.GE.R1.AND.FACT.LT.R2) GO TO 8
  10 CONTINUE
  FACT=FACT*10.**(-IDD)
  IS=IS+IDD
  ROUND MANTISSA TO 2 SIG FIGS
  IFAC=FACT*10.**.05
  FACT=IFAC
  FACT=FACT/10.
  IF(FACT.LT.10.) GO TO 20
  SET TJ 1 IF LESS THAN 10.
  FACT=1.
  IS=IS+1.
  IF INPUT NEGATIVE, SET MANTISSA NEGATIVE
  20 IF(ANUM.LT.0.) FACT=-FACT
  RETURN
  15 SET TO 0. IF 0.
  FACT=0.
  IS=0
  RETURN
END
  
```



```

C.....
SUBROUTINE UTPL0T
PURPOSE
    PRINTS GRAPHS ON THE STANDARD OUTPUT PRINTER
FEATURES
    1) FULL CONTROL OVER SCALING
    2) ABILITY TO PLOT SINGLE OR DOUBLE PRECISION VECTORS
CALLING SEQUENCE
CALL UTPL0T(X,Y,N,RANGE,K,MODCUR)
DESCRIPTION OF ARGUMENTS
X      VECTOR OF ABSCISSAE
Y      VECTOR OF ASSOCIATED ORDINATES
N      NUMBER OF (X,Y) PAIRS
RANGE  4 WORD SCALING VECTOR WHERE
        RANGE(1)= MAXIMUM X TO BE PLOTTED
        RANGE(2)= MINIMUM X TO BE PLOTTED
        RANGE(3)= MAXIMUM Y TO BE PLOTTED
        RANGE(4)= MINIMUM Y TO BE PLOTTED
        ALL (X,Y) POINTS OUTSIDE THE ABOVE RANGE WILL BE PLOTTED
        IN THE BORDER OF THE GRAPH.
K      EVERY KTH ELEMENT OF X & Y WILL BE PLOTTED, E.G.,
        FOR REAL#4 DATA (SINGLE PRECISION) K=1
        FOR REAL#8 DATA (DOUBLE PRECISION) K=2.
MODCUR  CONTROLS THE NUMBER OF CURVES ON ONE GRAPH
        =0 THERE IS ONLY 1 CURVE ON THIS GRAPH
        =1 THIS IS THE FIRST OF TWO OR MORE CURVES ON THIS GRAPH
        =2 THIS IS AN INTERMEDIATE CURVE ON THIS GRAPH
        =3 THIS IS THE LAST CURVE ON THIS GRAPH
C.....

```

```

UTPL0010
UTPL0020
UTPL0030
UTPL0040
UTPL0050
UTPL0060
UTPL0070
UTPL0080
UTPL0090
UTPL0100
UTPL0110
UTPL0120
UTPL0130
UTPL0140
UTPL0150
UTPL0160
UTPL0170
UTPL0180
UTPL0190
UTPL0200
UTPL0210
UTPL0220
UTPL0230
UTPL0240
UTPL0250
UTPL0260
UTPL0270
UTPL0280
UTPL0290
UTPL0300
UTPL0310
UTPL0320
UTPL0330
UTPL0340
UTPL0350
UTPL0360
UTPL0370
UTPL0380
UTPL0390
UTPL0400
UTPL0410
UTPL0420
UTPL0430
UTPL0440

```

CC

SCALING

SCALING IS PERFORMED ONLY ON THE FIRST SET OF POINTS (WHEN MODCUR = 0 OR 1.) ARRAY RANGE IS USED TO SET UP THE SCALE FACTORS AND NEED ONLY BE DEFINED FOR THE FIRST CALL TO UTPLOT.

GRID LABELLING

THE DATA TO BE GRAPHED WILL BE FIT INTO AN 80 COLUMN BY BY 60 ROW GRID. THE GRID WILL BE LABELLED THUSLY:
IN THE X DIRECTION (COLUMN-WISE), THERE WILL BE 5 VALUES: THE MAXIMUM, THE MINIMUM, AND 3 INTERMEDIATE AT INCREMENTS OF (RANGE(2)-RANGE(1))/4. FROM THE MINIMUM.
IN THE Y DIRECTION (ROW-WISE) THERE WILL BE 7 VALUES: THE MAXIMUM, THE MINIMUM, AND 5 INTERMEDIATE AT INCREMENTS OF (RANGE(4)-RANGE(3))/6. FROM THE MINIMUM.
IF THE LABELS HAVE A VALUE BETWEEN 1. AND 10**8, THEY WILL BE PRINTED IN AN F11.2 FORMAT, OTHERWISE THEY WILL BE PRINTED IN A 1PE10.3 FORMAT.

PLCTTING

FOUR CHARACTERS ARE USED FOR PLOTTING CURVES, ".", "+", "*", AND "X". WHEN MORE THAN 4 CURVES ARE PLOTTED THE CHARACTERS ARE USED REPEATEDLY. IF A NEW CURVE IS TO BE PLACED IN THE PLOTTING GRID WHERE AN OLD CURVE EXISTS, THE NEW CURVE REPLACES

UTPL0450
UTPL0460
UTPL0470
UTPL0480
UTPL0490
UTPL0500
UTPL0510
UTPL0520
UTPL0530
UTPL0540
UTPL0550
UTPL0560
UTPL0570
UTPL0590
UTPL0580
UTPL0600
UTPL0610
UTPL0620
UTPL0630
UTPL0640
UTPL0650
UTPL0660
UTPL0670
UTPL0680
UTPL0690
UTPL0700
UTPL0710
UTPL0720
UTPL0730

THE OLD CNE. THUS, IF 3 IDENTICAL CURVES ARE PLOTTED, THEY WILL
 APPEAR AS ONE CURVE COMPOSED OF "###".

MESSAGES

UNDER CERTAIN CIRCUMSTANCES, A PLOT WILL NOT BE OUTPUT AND
 ONE OF THE FOLLOWING MESSAGES WILL BE PRINTED ON THE STANDARD
 OUTPUT IN PLACE OF THE PLOT.

"ALL Y-VALUES=0. CANNOT SETUP PLOT GRID. CHECK MAX & MIN Y
 WHEN MDCUR=0 OR 1."

"ALL X VALUES=0. CANNOT SETUP PLOT GRID. CHECK MAX AND MIN X
 WHEN MDCUR=0 OR 1."

"GRID NOT SETUP WHEN MDCUR LAST 0 OR 1. NO PLOT UNTIL GRID
 PROPERLY SETUP."

NOTE

THE USER IS EXPECTED TO PROVIDE THE NECESSARY CARRIAGE
 CONTROLS TO PLACE THE GRAPH PROPERLY ON THE PAGE. BEFORE
 CALLING UTPLT THE USER SHOULD ISSUE A PRINT STATEMENT WHICH
 EJECTS A PAGE SO THAT THE GRAPH WILL BE PLOTTED AT THE TOP
 OF THE NEXT PAGE. A TITLE CAN BE PRINTED AT THE BOTTOM OF
 THE GRAPH BY ISSUING A PRINT STATEMENT RIGHT AFTER CALLING
 THE SUBROUTINE.

```

SUBROUTINE UTPLT (X, Y, NDATA, RANGE, KKZ, MDCUR)
  DIMENSION GRID(61,81), XSCALE(5), YSCALE(7)
  DIMENSION X(1), Y(1), RANGE(4)
  INTEGER#2 GRID, BLANK, DOT, XCHAR(4)/1H., 1H+, 1H*, 1HX/
  DATA DOT, BLANK/Z4840,Z4040/
  KDATA=NDATA*KKZ
  IF(MDCUR.GT.1) GO TO 444

```

GRID IS THE MATRIX USED TO PLOT THE POINTS

UTPL0740
 UTPL0750
 UTPL0760
 UTPL0770
 UTPL0780
 UTPL0790
 UTPL0800
 UTPL0810
 UTPL0820
 UTPL0830
 UTPL0840
 UTPL0850
 UTPL0860
 UTPL0870
 UTPL0880
 UTPL0890
 UTPL0900
 UTPL0910
 UTPL0920
 UTPL0930
 UTPL0940
 UTPL0950
 UTPL0960
 UTPL0970
 UTPL0980
 UTPL0990
 UTPL1000
 UTPL1010
 UTPL1020
 UTPL1030
 UTPL1040
 UTPL1050
 UTPL1060
 UTPL1070
 UTPL1080
 UTPL1090
 UTPL1100
 UTPL1110
 UTPL1120

```

C
      IERR=0
      XMAX=RANGE(1)
      XMIN=RANGE(2)
      YMAX=RANGE(3)
      YMIN=RANGE(4)
      CHECKING X AND Y POINTS AND PLOTTING THOSE OUT OF RANGE
      AT THE MARGIN
      DO 30 I=1,KDATA,KKZ
      IF(X(I).GT.XMAX.OR.X(I).LT.XMIN.OR.Y(I).GT.YMAX.OR.Y(I).LT.YMIN)
      1 IERR=IERR+1
      IF(X(I).LE.XMAX) GO TO 205
      X(I)=XMAX
      GO TO 210
      205 IF(X(I).GE.XMIN) GO TO 210
      X(I)=XMIN
      210 IF(Y(I).LE.YMAX) GO TO 215
      Y(I)=YMAX
      215 IF(Y(I).GE.YMIN) GO TO 30
      Y(I)=YMIN
      30 CONTINUE
      PLOTTING X AND Y AXIS , IF NECESSARY
      JERR=0
      X RANGE=XMAX-XMIN
      Y RANGE=YMAX-YMIN
      IF (YRANGE.NE.0.) GO TO 298
      IF (YMIN.EQ.0.) GO TO 889
      YMIN=0.
      UT PL 1130
      UT PL 1140
      UT PL 1150
      UT PL 1160
      UT PL 1170
      UT PL 1180
      UT PL 1190
      UT PL 1200
      UT PL 1210
      UT PL 1220
      UT PL 1230
      UT PL 1240
      UT PL 1250
      UT PL 1260
      UT PL 1270
      UT PL 1280
      UT PL 1290
      UT PL 1300
      UT PL 1310
      UT PL 1320
      UT PL 1330
      UT PL 1340
      UT PL 1350
      UT PL 1360
      UT PL 1370
      UT PL 1380
      UT PL 1390
      UT PL 1400
      UT PL 1410
      UT PL 1420
      UT PL 1430
      UT PL 1440
      UT PL 1450
      UT PL 1460

```

```

YRANGE=YMAX
GO TO 299
298 IF (XRANGE.NE.0.) GO TO 299
   IF (XMIN.EQ.0.) GO TO 887
   XMIN=0.
   XRANGE=XMAX
C
C      BLANKING OUT MATRIX-(GRID)
C
299 DO 300 I=1,61
   DO 301 JJ=1,81
   GRID(I,JJ)=BLANK
301 CONTINUE
300 IF (XMAX*XMIN.GE.0.) GO TO 222
   IXAXIS=80.*(-XMIN)/XRANGE+1.5
   DO 40 I=1,61
   GRID(I,IXAXIS)=DOT
40 CONTINUE
222 IF (YMAX*YMIN.GE.0.) GO TO 333
   IXAXIS=60.*YMAX/YRANGE+1.5
   DO 60 I=1,81
   GRID(IXAXIS,I)=DOT
60 CONTINUE
C
C      COMPUTE PROPER SCALE NUMBERS
C
333 XINCR=XRANGE/4.
   YINCR=YRANGE/6.
   XSCALE(1)=XMAX
   XSCALE(5)=XMIN
   DO 80 I=2,4
   XSCALE(I)=XSCALE(I-1)-XINCR
   IF (ABS(XSCALE(I)).LT.1.E-4) XSCALE(I)=0.
80 CONTINUE
   YSCALE(1)=YMAX
   YSCALE(7)=YMIN
   DO 81 I=2,6
   YSCALE(I)=YSCALE(I-1)-YINCR
   IF (ABS(YSCALE(I)).LT.1.E-4) YSCALE(I)=0.
81 CONTINUE
   DO 85 II=1,2
   JJ=6-II
   XT=XSCALE(JJ)
   XSCALE(JJ)=XSCALE(II)
85 XSCALE(II)=XT

```

```

UT PL 1470
UT PL 1480
UT PL 1490
UT PL 1500
UT PL 1510
UT PL 1520
UT PL 1530
UT PL 1540
UT PL 1550
UT PL 1560
UT PL 1570
UT PL 1580
UT PL 1590
UT PL 1600
UT PL 1610
UT PL 1620
UT PL 1630
UT PL 1640
UT PL 1650
UT PL 1660
UT PL 1670
UT PL 1680
UT PL 1690
UT PL 1700
UT PL 1710
UT PL 1720
UT PL 1730
UT PL 1740
UT PL 1750
UT PL 1760
UT PL 1770
UT PL 1780
UT PL 1790
UT PL 1800
UT PL 1810
UT PL 1820
UT PL 1830
UT PL 1840
UT PL 1850
UT PL 1860
UT PL 1870
UT PL 1880
UT PL 1890

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UT PL 1900
UT PL 1910
UT PL 1920
UT PL 1930
UT PL 1940
UT PL 1950
UT PL 1960
UT PL 1970
UT PL 1980
UT PL 1990
UT PL 2000
UT PL 2010
UT PL 2020
UT PL 2030
UT PL 2040
UT PL 2050
UT PL 2060
UT PL 2070
UT PL 2080
UT PL 2090
UT PL 2100
UT PL 2110
UT PL 2120
UT PL 2130
UT PL 2140
UT PL 2150
UT PL 2160
UT PL 2170
UT PL 2180
UT PL 2190

PLACING POINTS IN THEIR PROPER GRID POSITIONS

444 IF (MODCUR.LT.2) JSET=0
IF (JERR.GT.0) GO TO 885
JSET=JSET+1

DO 700 I=1,KDATA,KKZ
IPTX=60.*(YMAX-Y(I))/YRANGE+1.5
IPTY=80.*(X(I)-XMIN)/XRANGE+1.5
IF (IPTX.GT.61.OR.IPTY.GT.81) GO TO 70
IF (IPTX.LE.0.OR.IPTY.LE.0) GO TO 70
GRID(IPTX,IPTY) = XCHAR(JSET)
GO TO 700

70 JERR=JERR+1

700 CONTINUE

OUTPUT SECTION WITH GRAPH

IF (MODCUR.EQ.1.OR.MODCUR.EQ.2) RETURN

AXR=ABS(XRANGE)

AYR=ABS(YRANGE)

IF (AXR.LT.1.E+8.AND.AXR.GE..95) GO TO 400

WRITE(6,17) XSCALE

FORMAT(12X,1PE10.3,4(10X,E10.3)/15X,'*',8('++++*****'),'+***,')

17 GO TO 401

400 WRITE(6,117) XSCALE

117 FORMAT(8X,F11.2,4(9X,F11.2)/15X,'*',8('++++*****'),'+***,')

401 II=1

DO 101 IK=1,61

IF (MOD(IK-1,10).NE.0) GO TO 92

IF (AYR.LT.1.E+8.AND.AYR.GE..95) GO TO 404

WRITE(6,18) YSCALE(II),(GRID(IK,IX),IX=1,81),YSCALE(II)

FORMAT(3X,1PE10.3,2X,1H+,1X,81A1,1X,1H+,2X,E10.3)

18 GO TO 405

404 WRITE(6,118) YSCALE(II),(GRID(IK,IX),IX=1,81),YSCALE(II)

118 FORMAT(12X,F11.2,'+',81A1,'+',F11.2)

405 II=II+1

GO TO 101

92 WRITE(6,19) (GRID(IK,IX),IX=1,81)

19 FORMAT(15X,'*',81A1,'*')

101 CONTINUE

IF (AXR.LT.1.E+8.AND.AXR.GE..95) GO TO 402

WRITE(6,22) XSCALE

FORMAT(15X,'*',8('++++*****'),'+***/12X,1PE10.3,4(10X,E10.3),//)

22 GO TO 403

402 WRITE(6,217) XSCALE

217 FORMAT(15X,'*',8('++++*****'),'+***/8X,F11.2,4(9X,F11.2),//)

219 IF (JERR.GT.0) WRITE(6,20) JERR

20 FORMAT(10X,'NUMBER OF POINTS OUT OF RANGE =',I4)

1000 RETURN

889 WRITE(6,888)

888 FORMAT(' ALL Y VALUES=0. CANNOT SETUP PLOT GRID. CHECK MAX & MIN')

1 WHEN MODCUR=0 OR 1.')

JERR=10

RETURN

887 WRITE(6,896)

886 FORMAT(' ALL X VALUES=0. CANNOT SETUP PLOT GRID. CHECK MAX & MIN')

1 WHEN MODCUR=0 OR 1.')

JERR=10

RETURN

885 WRITE(6,894)

884 FORMAT(' GRID NOT SETUP WHEN MODCUR LAST 0 OR 1. NO PLOT UNTIL GRID')

ERROR DETECTION MODEL FIGURE 1

20 INPUTS									
6	12	R	1.00000	0.33333					
12	3	R	0.50000	0.25000					
12	16		0.50000	0.50000					
11	13		1.00000	0.08333					
13	16		1.00000	0.16667					
14	16		1.00000	0.25000					
7	11		0.50000	0.08333					
8	14		1.00000	0.16667					
1	2		1.00000	1.00000					
2	3		0.50000	0.50000					
2	4		0.50000	0.50000					
4	7		0.33333	0.16667					
4	8		0.33333	0.16667					
4	9		0.33333	0.16667					
7	10		0.50000	0.08333					
9	14		0.50000	0.08333					
9	15		0.50000	0.08333					
10	13		1.00000	0.08333					
15	16		1.00000	0.08333					
3	5	R	0.50000	0.33333					
3	6	R	0.50000	0.33333					
5	12	R	1.00000	0.33333					
000									
.6			.6	.6	.6	.6	.6	.6	.6
.6			.6	.6	.6	.6	.6	.6	.6
.6			.6	.6	.6	.6	.6	.6	.6

Card input to program EXP

PROGRAM TITLE: ERROR DETECTION-MODEL—FIGURE-1

INPUTS = 20

NUMBER OF ARCS = 22

TAIL	ARC HEAD	BRANCH PROB.	TRAVERSAL PROB.	EXPECTED NUMBER OF ERRORS
6	12	1.0000	0.3333	0.60
12	3	0.5000	0.2500	0.60
12	16	0.5000	0.5000	0.60
11	13	1.0000	0.0833	0.60
13	16	1.0000	0.1667	0.60
14	16	1.0000	0.2500	0.60
7	11	0.5000	0.0833	0.60
8	14	1.0000	0.1667	0.60
1	2	1.0000	1.0000	0.60
2	3	0.5000	0.5000	0.60
2	4	0.5000	0.5000	0.60
4	7	0.3333	0.1667	0.60
4	8	0.3333	0.1667	0.60
4	9	0.3333	0.1667	0.60
7	10	0.5000	0.0833	0.60
9	14	0.5000	0.0833	0.60
9	15	0.5000	0.0833	0.60
10	13	1.0000	0.0833	0.60
15	16	1.0000	0.0833	0.60
3	5	0.5000	0.3333	0.60
3	6	0.5000	0.3333	0.60
5	12	1.0000	0.3333	0.60

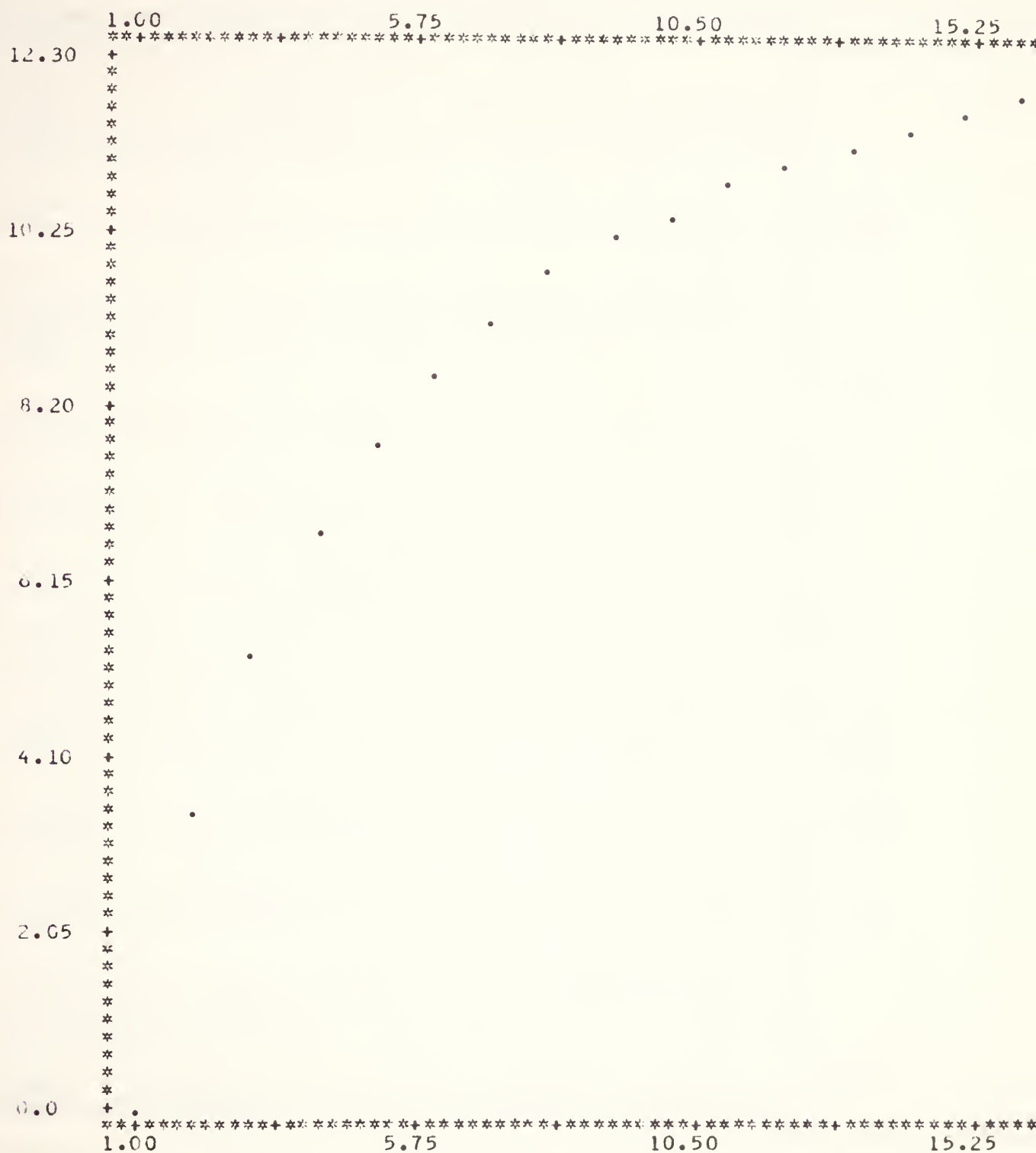
INITIAL EXPECTED NUMBER OF ERRORS= 13.20

INPUT	EXPECTED NUMBER OF ERRORS DETECTED	CUMMULATIVE EXPECTED NUMBER OF ERRORS DETECTED
1	3.45	3.45
2	1.95	5.40
3	1.39	6.79
4	1.04	7.82
5	0.80	8.62
6	0.63	9.25
7	0.51	9.76
8	0.42	10.19
9	0.36	10.54
10	0.30	10.85
11	0.26	11.10
12	0.22	11.33
13	0.20	11.52
14	0.17	11.69
15	0.15	11.84
16	0.13	11.98
17	0.12	12.10
18	0.11	12.20
19	0.09	12.30
20	0.08	12.38

Output of program EXP

GRAPH OF CUMMULATIVE EXPECTED NUMBER OF ERRORS DETECTED -VS- NUMBER OF INPUTS.

PROGRAM TITLE: ERROR DETECTION MODEL FIGURE 1



X-SCALE: "*"= 0.237E 00 UNITS

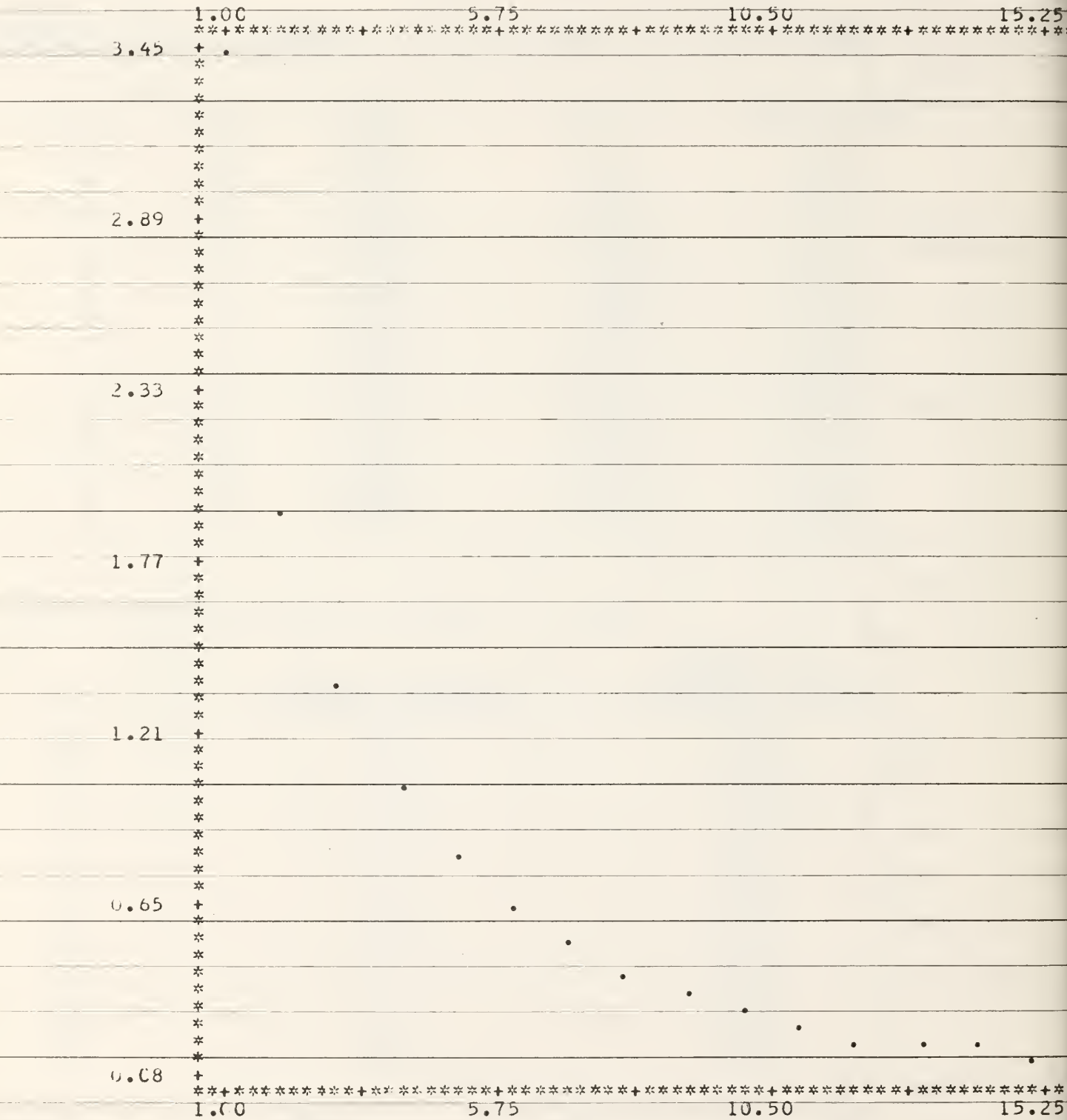
Y-SCALE: "*"= 0.205E 00 UNITS

INPUT NUMBER

Output of program EXP

GRAPH OF EXPECTED NUMBER OF ERRORS DETECTED -VS- NUMBER OF INPUTS.

PROGRAM TITLE: ERROR DETECTION MODEL FIGURE 1



X-SCALE: "*"= 0.237E 00 UNITS

Y-SCALE: "*"= 0.561E 01 UNITS

INPUT NUMBER

Output of program EXP

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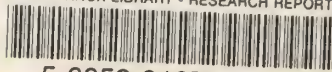
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